



Specifications and information are subject to change without notice. Up-to-date address information is available on our website.

web: www.smar.com/contactus.asp

# INTRODUCTION

The **LD291** is a smart pressure transmitter for gauge and level measurement. It is based on a field-proven capacitive sensor that provides reliable operation and high performance. The digital technology used in the **LD291** enables an easy interface between the field and the control room and several interesting features that considerably reduce the installation, operation and maintenance costs.

The **LD291** is the economical alternative in routine gage pressure measurement. This lightweight design eliminates the need for mounting brackets and transmitter supports in many applications.

The model **LD291** offers digital HART<sup>®</sup> based communication simplifying calibration and providing remote diagnostics. Also, an optional LCD meter can be added to provide additional operations and local indication.

Its microprocessor- based electronics allow for total interchangeability with SMAR capacitive sensors. It automatically corrects sensor characteristic changes caused by temperature fluctuations.

- The **LD291**, besides the normal functions offered by other smart transmitters, offers the following functions:
- ✓ TABLE the pressure signal is custom linearized according to a 16-point table, enabling, e.g., conversion of level to volume of a horizontal cylindrical tank.
- ✓ LOCAL ADJUSTMENT not only for lower and upper value, but input/output function, indication, as well.
- ✓ **PASSWORD** three levels for different functions.
- OPERATION COUNTER shows the number of changes in each function.
- USER-UNIT indication in engineering unit of the property actually measured, e.g., level, flow or volume.
- ✓ WRITE-PROTECT- via hardware.

Get the best results of the LD291 by carefully reading these instructions.

Smar's pressure transmitters are protected by U.S. patents 6,433,791 and 6,621,443.

NOTE

This manual is compatible with version 6.XX, where 6 denote software version and XX software release. The indication 6.XX means that this manual is compatible with any release of software version 6.

WARNING

To ensure that our products are safe and without risk to health, the manual must be read carefully before proceeding and warning labels on packages must be observed. Installation, operation, maintenance and servicing must only be carried out by suitably trained personnel and in accordance with the **Operation and Maintenance Instruction Manual**.

### Waiver of responsibility

The contents of this manual abides by the hardware and software used on the current equipment version. Eventually there may occur divergencies between this manual and the equipment. The information from this document are periodically reviewed and the necessary or identified corrections will be included in the following editions. Suggestions for their improvement are welcome.

## Warning

For more objectivity and clarity, this manual does not contain all the detailed information on the product and, in addition, it does not cover every possible mounting, operation or maintenance cases.

Before installing and utilizing the equipment, check if the model of the acquired equipment complies with the technical requirements for the application. This checking is the user's responsibility.

If the user needs more information, or on the event of specific problems not specified or treated in this manual, the information should be sought from Smar. Furthermore, the user recognizes that the contents of this manual by no means modify past or present agreements, confirmation or judicial relationship, in whole or in part.

All of Smar's obligation result from the purchasing agreement signed between the parties, which includes the complete and sole valid warranty term. Contractual clauses related to the warranty are not limited nor extended by virtue of the technical information contained in this manual.

Only qualified personnel are allowed to participate in the activities of mounting, electrical connection, startup and maintenance of the equipment. Qualified personnel are understood to be the persons familiar with the mounting, electrical connection, startup and operation of the equipment or other similar apparatus that are technically fit for their work. Smar provides specific training to instruct and qualify such professionals. However, each country must comply with the local safety procedures, legal provisions and regulations for the mounting and operation of electrical installations, as well as with the laws and regulations on classified areas, such as intrinsic safety, explosion proof, increased safety and instrumented safety systems, among others.

The user is responsible for the incorrect or inadequate handling of equipments run with pneumatic or hydraulic pressure or, still, subject to corrosive, aggressive or combustible products, since their utilization may cause severe bodily harm and/or material damages.

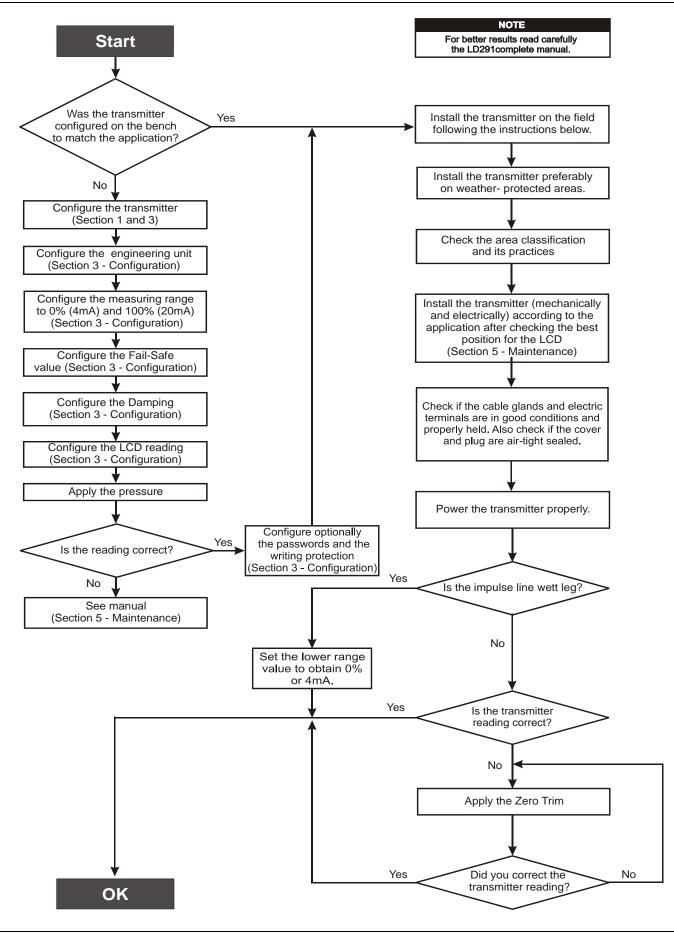
The field equipment referred to in this manual, when acquired for classified or hazardous areas, has its certification void when having its parts replaced or interchanged without functional and approval tests by Smar or any of Smar authorized dealers, which are the competent companies for certifying that the equipment in its entirety meets the applicable standards and regulations. The same is true when converting the equipment of a communication protocol to another. In this case, it is necessary sending the equipment to Smar or any of its authorized dealer. Moreover, the certificates are different and the user is responsible for their correct use.

Always respect the instructions provided in the Manual. Smar is not responsible for any losses and/or damages resulting from the inadequate use of its equipments. It is the user's responsibility to know and apply the safety practices in his country.

# TABLE OF CONTENTS

ELECTRONIC HOUSING         18           WIRING         19           LOOP CONECTIONS         110           INSTALLATION IN HAZARDOUS AREAS         112           EXPLOSIONFLAME PROOF         112           INTRINSICALLY SAFE         112           INTRINSICALLY SAFE         112           SECTION 2 - OPERATION         SENSOR           FUNCTIONAL DESCRIPTION - SENSOR         21           FUNCTIONAL DESCRIPTION - HARDWARE         22           FUNCTIONAL DESCRIPTION - SOFTWARE         23           THE DISPLAY         25           SECTION 3 - CONFIGURATION         301           CONFIGURATION FEATURES         33           MANUFACTURING DATA AND DENTIFICATION         33           PRIMARY VARIABLE TRIM - PRESSURE         33           PRIMARY VARIABLE CURRENT TRIM         34           TRANSMITTER ADJUSTINENT TO THE WORKING RANGE         36           ENGINEERING UNIT SELECTION         36           TABLE POINTS         37           EQUIPMENT CONFIGURATION         38           EQUIPMENT MAINTENANCE         38           SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.         41           THE MAGNETIC TOOL         41           SIMMEL LOCAL ADJUSTMENT         42 <th>SECTION 1 - INSTALLATION</th> <th> 1.1</th>	SECTION 1 - INSTALLATION	1.1
FUNCTIONAL DESCRIPTION - SOFTWARE       23         THE DISPLAY       25         SECTION 3 - CONFIGURATION       31         CONFIGURATION FEATURES       33         MANUFACTURING DATA AND IDENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE URRENT TRIM       34         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       36         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       36         EQUIPMENT CONFIGURATION       36         EQUIPMENT CONFIGURATION       36         EQUIPMENT MINITENANCE       37         ECONPMENT MAINTENANCE       38         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       41         THE MAGNETIC TOOL       41         SIMPLE LOCAL ADJUSTMENT       42         COMPLETE LOCAL ADJUSTMENT       42         CONFIGURATION ICONFJ.       43         CONFIGURATION RERANGING       42         CONFIGURATION NERANCH (CONF)       43         CONFIGURATION RERANGING       42         CONFIGURATION NEANCH (CONF)       44         RANGE (RANGE)       45         RANGE (RANGE)       45         <	GENERAL	
WIRING         19           LOOP CONECTIONS         110           INSTALLATION IN HAZARDOUS AREAS         112           EXPLOSION/FLAME PROOF         112           INTRINSICALLY SAFE         112           SECTION 2 - OPERATION         21           FUNCTIONAL DESCRIPTION + NARDWARE         21           FUNCTIONAL DESCRIPTION - SENSOR         21           FUNCTIONAL DESCRIPTION - MARDWARE         22           FUNCTIONAL DESCRIPTION - MARDWARE         22           FUNCTIONAL DESCRIPTION - MARDWARE         23           THE DISPLAY         25           SECTION 3 - CONFIGURATION         33           MANUFACTURING DATA AND IDENTIFICATION         33           PRIMARY VARIABLE CURRENT TRIM         34           TRANSMITTER ADJUSTIKENT TO THE WORKING RANGE         36           ENGINEERING UNIT SELECTION         37           TABLE POINTS         37           EQUIPMENT CONFIGURATION         38           EQUIPMENT CONFIGURATION         38           EQUIPMENT CONFIGURATION         38           EQUIPMENT CONFIGURATION         37           THE MAGNETIC TOOL         41           THE MAGNETIC TOOL         41           SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.         4	MOUNTING	
LOOP CONECTIONS.       110         INSTALLATION IN HAZARDOUS AREAS.       112         EXPLOSION/FLAME PROOF       112         INTRINSICALLY SAFE       112         INTRINSICALLY SAFE       112         SECTION 2 - OPERATION.       21         FUNCTIONAL DESCRIPTION - SENSOR       21         FUNCTIONAL DESCRIPTION - HARDWARE       22         FUNCTIONAL DESCRIPTION - SOFTWARE       23         SECTION 3 - CONFIGURATION.       31         CONFIGURATION FEATURES.       33         MANUPACTURING DATA AND DENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE CURRENT TRIM       34         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       35         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       38         EQUIPMENT CONFIGURATION       38         EQUIPMENT MAINTENANCE       38         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       41         THE MAGNETIC TOOL       41         THE MAGNETIC TOOL       41         SIMPLE LOCAL ADJUSTMENT       42         ZERTON 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       42         CONFIGURATION BRA	ELECTRONIC HOUSING	
INSTALLATION IN HAZARDOUS AREAS.       1.12         EXPLOSIONFLAME PROOF       1.12         INTRINSICALLY SAFE       1.12         SECTION 2 - OPERATION       2.1         FUNCTIONAL DESCRIPTION + MARDWARE       2.1         FUNCTIONAL DESCRIPTION - SENSOR       2.1         FUNCTIONAL DESCRIPTION - SENSOR       2.1         FUNCTIONAL DESCRIPTION - SOFTWARE       2.3         THE DISPLAY       2.5         SECTION 3 - CONFIGURATION       3.1         CONFIGURATION FEATURES       3.3         MANUFACTURING DATA AND IDENTIFICATION       3.3         PRIMARY VARIABLE CURRENT TRIM       3.4         TRANSWITTER ADJUSTMENT TO THE WORKING RANGE       3.5         ENGINEERING UNIT SELECTION       3.6         TABLE POINTS       3.7         EQUIPMENT MAINTENANCE       3.8         ECOUPMENT CONFIGURATION       3.8         ECOUPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN REANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE BR		
EXPLOSION/FLAME PROOF       112         INTRINSICALLY SAFE       112         SECTION 2 - OPERATION       21         FUNCTIONAL DESCRIPTION - SENSOR       21         FUNCTIONAL DESCRIPTION - MARDWARE       22         FUNCTIONAL DESCRIPTION - SOFTWARE       23         THE DISPLAY       25         SECTION 3 - CONFIGURATION       30         MANUPACTURING DATA AND DENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE TRIM - PRESSURE       35         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       38         EQUIPMENT CONFIGURATION       38         EQUIPMENT CONFIGURATION       38         EQUIPMENT MAINTENANCE       38         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       41         THE MAGNETIC TOOL       41         THE MAGNETIC TOOL       41         SIMPLE LOCAL ADJUSTMENT       42         ZERO AND SPAN RERANGING       42         CONFIGURATION BARACH (CONF)       44         RANGE (RANGE)       45         RANGE (RANGE)       45         RA	LOOP CONECTIONS	
INTRINSICALLY SAFE       1.12         SECTION 2 - OPERATION       2.1         FUNCTIONAL DESCRIPTION - SENSOR       2.1         FUNCTIONAL DESCRIPTION - HARDWARE       2.2         FUNCTIONAL DESCRIPTION - SOFTWARE       2.3         THE DISPLAY       2.5         SECTION 3 - CONFIGURATION       3.1         CONFIGURATION FEATURES       3.3         MANUFACTURING DATA AND IDENTIFICATION       3.3         PRIMARY VARIABLE TRIM - PRESSURE       3.6         TABLE POINTS       3.6         TABLE POINTS       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         EQUIPMENT MAINTENANCE       3.8         EQUIPMENT MAINTENANCE       3.8         EQUIPMENT CONFIGURATION       4.1         TIME MAGNETIC TOOL       4.1         TIME MAGNETIC TOOL       4.1         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1	INSTALLATION IN HAZARDOUS AREAS	
SECTION 2 - OPERATION	EXPLOSION/FLAME PROOF	
FUNCTIONAL DESCRIPTION - SENSOR       21         FUNCTIONAL DESCRIPTION - HARDWARE       22         FUNCTIONAL DESCRIPTION - SOFTWARE       23         THE DISPLAY       25         SECTION 3 - CONFIGURATION       31         CONFIGURATION FEATURES       33         MANUFACTURING DATA AND IDENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE CURRENT TRIM       34         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       35         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       38         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT       41         SIMPLE LOCAL ADJUSTMENT       41         SIMPLE LOCAL ADJUSTMENT       42         COMPLETE LOCAL ADJUSTMENT       42         COMPLETE LOCAL ADJUSTMENT       43         LOCAL PROGRAMMING TREE       43         LOCAL PROGRAMMING TREE       43         CONFIGURATION ISONF       44         RANGE (RANGE)       45         RANGE (RAN	INTRINSICALLY SAFE	
FUNCTIONAL DESCRIPTION - SENSOR       21         FUNCTIONAL DESCRIPTION - HARDWARE       22         FUNCTIONAL DESCRIPTION - SOFTWARE       23         THE DISPLAY       25         SECTION 3 - CONFIGURATION       31         CONFIGURATION FEATURES       33         MANUFACTURING DATA AND IDENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE CURRENT TRIM       34         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       35         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       38         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT       41         SIMPLE LOCAL ADJUSTMENT       41         SIMPLE LOCAL ADJUSTMENT       42         COMPLETE LOCAL ADJUSTMENT       42         COMPLETE LOCAL ADJUSTMENT       43         LOCAL PROGRAMMING TREE       43         LOCAL PROGRAMMING TREE       43         CONFIGURATION ISONF       44         RANGE (RANGE)       45         RANGE (RAN	SECTION 2 - OPERATION	2 1
FUNCTIONAL DESCRIPTION - HARDWARE       22         FUNCTIONAL DESCRIPTION - SOFTWARE       23         THE DISPLAY       25         SECTION 3 - CONFIGURATION       31         CONFIGURATION FEATURES       33         MANUFACTURING DATA AND IDENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE TRIM - PRESSURE       35         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       38         EQUIPMENT CONFIGURATION       38         EQUIPMENT CONFIGURATION       36         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT       41         THE MAGNETIC TOOL       41         THE MAGNETIC TOOL       41         SIMPLE COCAL ADJUSTMENT       42         ZERO AND SPAN RERANGING.       42         COMPLETE LOCAL ADJUSTMENT       42         LOCAL PROGRAMMING TREE       43         CONFIGURATION ICONFI.       43         CONFIGURATION NEANCH (CONF)       44         RANGE (RANCE)       45         RANGE BRANCH (RANGE)       45         RANGE BRANCH (RANGE)       45 <t< td=""><td></td><td></td></t<>		
FUNCTIONAL DESCRIPTION - SOFTWARE       23         THE DISPLAY       25         SECTION 3 - CONFIGURATION       31         CONFIGURATION FEATURES       33         MANUFACTURING DATA AND IDENTIFICATION       33         PRIMARY VARIABLE TRIM - PRESSURE       33         PRIMARY VARIABLE URRENT TRIM       34         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       36         ENGINEERING UNIT SELECTION       36         TABLE POINTS       37         EQUIPMENT CONFIGURATION       36         EQUIPMENT CONFIGURATION       36         EQUIPMENT CONFIGURATION       36         EQUIPMENT MINITENANCE       37         ECONPMENT MAINTENANCE       38         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       41         THE MAGNETIC TOOL       41         SIMPLE LOCAL ADJUSTMENT       42         COMPLETE LOCAL ADJUSTMENT       42         CONFIGURATION ICONFJ.       43         CONFIGURATION RERANGING       42         CONFIGURATION NERANCH (CONF)       43         CONFIGURATION RERANGING       42         CONFIGURATION NEANCH (CONF)       44         RANGE (RANGE)       45         RANGE (RANGE)       45         <		
THE DISPLAY.       2.5         SECTION 3 - CONFIGURATION       3.1         CONFIGURATION FEATURES.       3.3         MANUFACTURING DATA AND IDENTIFICATION       3.3         PRIMARY VARIABLE TRIM - PRESSURE       3.3         PRIMARY VARIABLE CURRENT TRIM       3.4         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       3.6         ENGINEERING UNIT SELECTION       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         TIME LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.3         CONFIGURATION [CONF].       4.3         CONFIGURATION BRANCH (CONF).       4.4         RANGE (RANGE).       4.5         RANGE (RANGE).		
CONFIGURATION FEATURES		
CONFIGURATION FEATURES		
MANUFACTURING DATA AND IDENTIFICATION       3.3         PRIMARY VARIABLE TRIM - PRESSURE       3.3         PRIMARY VARIABLE CURRENT TRIM       3.4         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       3.5         ENGINEERING UNIT SELECTION       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         TIME MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         ZERO AND SPAN RERANGING       4.2         COMFIGURATION [CONF]       4.3         CONFIGURATION CONFJ       4.3         CONFIGURATION CONFJ       4.5         RANGE (RANGE)       4.5         RANGE (RANGE)       4.5         FUNCTION (FUNCT)       4.5         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1<		
PRIMARY VARIABLE TRIM - PRESSURE       3.3         PRIMARY VARIABLE CURRENT TRIM       3.4         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       3.5         ENGINEERING UNIT SELECTION       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING.       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         RANGE BRANCH (RANGE)       4.5         RANGE BRANCH (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1 </td <td></td> <td></td>		
PRIMARY VARIABLE CURRENT TRIM       3.4         TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       3.5         ENGINEERING UNIT SELECTION       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION (CONF)       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         RANGE (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABLITY       5.5         RETURNING MATERIALS       5.6 <tr< td=""><td></td><td></td></tr<>		
TRANSMITTER ADJUSTMENT TO THE WORKING RANGE       3.5         ENGINEERING UNIT SELECTION       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION ICONFJ       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE BRANCH (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DIAGNOSTIC WITH THE TRANSMITTER       5.5         INTERCHANGEABLITY       5.5         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DIAGNOSTIC WITH THE TRANSMITTER       5.5         DIAGNOSTIC WI		
ENGINEERING UNIT SELECTION.       3.6         TABLE POINTS       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT.       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION BRANCH (CONF)       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         FUNCTION (FUNCT)       4.5         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERROR MESSAGES       5.1         DISASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4	PRIMARY VARIABLE CURRENT TRIM	
TABLE POINTS.       3.7         EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING.       4.2         COMPLETE LOCAL ADJUSTMENT       4.2         LOCAL PROGRAMMING TREE       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION [CONF]       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         RANGE BRANCH (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERROR MESSAGES       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DIAGNOSTIC WITH THE TRANSMITTER       5.5         INTERCHANGEABILLY PROCEDURE       5.5         INTERCHANGEABILLY PROCEDURE       5.5	TRANSMITTER ADJUSTMENT TO THE WORKING RANGE	
EQUIPMENT CONFIGURATION       3.8         EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION [CONF]       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         RANGE (RANGE)       4.5         FUNCTION (FUNCT)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERROR MESSAGES       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGE ABILITY       5.5         INTERCHANGE ABILITY       5.5         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING	ENGINEERING UNIT SELECTION	
EQUIPMENT MAINTENANCE       3.8         SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION [CONF]       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE BRANCH (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERNOR MESSAGES       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.5         INTERCHANGEABLITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
SECTION 4 - PROGRAMMING USING LOCAL ADJUSTMENT.       4.1         THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING.       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION (CONF).       4.3         CONFIGURATION BRANCH (CONF).       4.4         RANGE (RANGE).       4.5         RANGE BRANCH (RANGE).       4.5         FUNCTION (FUNCT).       4.7         PRESSURE TRIM [TRIM].       4.8         ESCAPE LOCAL ADJUSTMENT [ESC].       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4	EQUIPMENT CONFIGURATION	
THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION [CONF]       4.3         CONFIGURATION BRANCH (CONF)       4.3         RANGE (RANGE)       4.5         FUNCTION (FUNCT)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4	EQUIPMENT MAINTENANCE	
THE MAGNETIC TOOL       4.1         SIMPLE LOCAL ADJUSTMENT       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION [CONF]       4.3         CONFIGURATION BRANCH (CONF)       4.3         RANGE (RANGE)       4.5         FUNCTION (FUNCT)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
SIMPLE LOCAL ADJUSTMENT.       4.2         ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE.       4.3         CONFIGURATION [CONF].       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         RANGE BRANCH (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
ZERO AND SPAN RERANGING       4.2         COMPLETE LOCAL ADJUSTMENT       4.3         LOCAL PROGRAMMING TREE       4.3         CONFIGURATION [CONF]       4.3         CONFIGURATION BRANCH (CONF)       4.4         RANGE (RANGE)       4.5         RANGE BRANCH (RANGE)       4.5         FUNCTION (FUNCT)       4.7         PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
COMPLETE LOCAL ADJUSTMENT4.3LOCAL PROGRAMMING TREE4.3CONFIGURATION [CONF]4.3CONFIGURATION BRANCH (CONF)4.4RANGE (RANGE)4.5RANGE BRANCH (RANGE)4.5FUNCTION (FUNCT)4.7PRESSURE TRIM [TRIM]4.8ESCAPE LOCAL ADJUSTMENT [ESC]4.10SECTION 5 - MAINTENANCE PROCEDURES5.1GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
LOCAL PROGRAMMING TREE4.3CONFIGURATION [CONF].4.3CONFIGURATION BRANCH (CONF).4.4RANGE (RANGE)4.5RANGE BRANCH (RANGE).4.5FUNCTION (FUNCT)4.7PRESSURE TRIM [TRIM].4.8ESCAPE LOCAL ADJUSTMENT [ESC].4.10SECTION 5 - MAINTENANCE PROCEDURESS15.1GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
CONFIGURATION [CONF]		
CONFIGURATION BRANCH (CONF)4.4RANGE (RANGE)4.5RANGE BRANCH (RANGE)4.5FUNCTION (FUNCT)4.7PRESSURE TRIM [TRIM]4.8ESCAPE LOCAL ADJUSTMENT [ESC]4.10SECTION 5 - MAINTENANCE PROCEDURES5.1GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
RANGE (RANGE)4.5RANGE BRANCH (RANGE)4.5FUNCTION (FUNCT)4.7PRESSURE TRIM [TRIM]4.8ESCAPE LOCAL ADJUSTMENT [ESC]4.10SECTION 5 - MAINTENANCE PROCEDURES5.1GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
RANGE BRANCH (RANGE)4.5FUNCTION (FUNCT)4.7PRESSURE TRIM [TRIM]4.8ESCAPE LOCAL ADJUSTMENT [ESC]4.10SECTION 5 - MAINTENANCE PROCEDURES5.1GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
FUNCTION (FUNCT)4.7PRESSURE TRIM [TRIM]4.8ESCAPE LOCAL ADJUSTMENT [ESC]4.10SECTION 5 - MAINTENANCE PROCEDURES5.1GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
PRESSURE TRIM [TRIM]       4.8         ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERROR MESSAGES       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
ESCAPE LOCAL ADJUSTMENT [ESC]       4.10         SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERROR MESSAGES       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4	FUNCTION (FUNCT)	
SECTION 5 - MAINTENANCE PROCEDURES       5.1         GENERAL       5.1         DIAGNOSTIC WITH THE CONFIGURATOR       5.1         ERROR MESSAGES       5.1         DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4	PRESSURE TRIM [TRIM]	
GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4	ESCAPE LOCAL ADJUSTMENT [ESC]	4.10
GENERAL5.1DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4	SECTION 5 - MAINTENANCE PROCEDURES	F 1
DIAGNOSTIC WITH THE CONFIGURATOR5.1ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
ERROR MESSAGES5.1DIAGNOSTIC WITH THE TRANSMITTER5.2DISASSEMBLY PROCEDURE5.4REASSEMBLY PROCEDURE5.5INTERCHANGEABILITY5.5RETURNING MATERIALS5.6ORDERING CODE FOR SENSOR5.9SECTION 6 - TECHNICAL CHARACTERISTICS6.1ORDERING CODE6.4		
DIAGNOSTIC WITH THE TRANSMITTER       5.2         DISASSEMBLY PROCEDURE       5.4         REASSEMBLY PROCEDURE       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
DISASSEMBLY PROCEDURE.       5.4         REASSEMBLY PROCEDURE.       5.5         INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
REASSEMBLY PROCEDURE		
INTERCHANGEABILITY       5.5         RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
RETURNING MATERIALS       5.6         ORDERING CODE FOR SENSOR       5.9         SECTION 6 - TECHNICAL CHARACTERISTICS       6.1         ORDERING CODE       6.4		
ORDERING CODE FOR SENSOR		
SECTION 6 - TECHNICAL CHARACTERISTICS		
ORDERING CODE		
	SECTION 6 - TECHNICAL CHARACTERISTICS	
OPTIONAL ITEMS	ORDERING CODE	
	OPTIONAL ITEMS	

OPTIONAL ITEMS	6.7
OPTIONAL ITEMS	6.9
OPTIONAL ITEMS	6.11
APPENDIX A - CERTIFICATIONS INFORMATIONS	A.1
EUROPEAN DIRECTIVE INFORMATION	A.1
OTHER APROVALS	A.1
FMEDA REPORT	A.1
HAZARDOUS LOCATIONS CERTIFICATIONS	A.1
NORTH AMERICAN CERTIFICATIONS	A.1
EUROPEAN CERTIFICATIONS	
SOUTH AMERICAN CERTIFICATIONS	A.2
ASIAN CERTIFICATIONS	A.3
IDENTIFICATION PLATE AND CONTROL DRAWING	A.3
IDENTIFICATION PLATE	
CONTROL DRAWING	A.7
APPENDIX B – SRF – SERVICE REQUEST FORM	B.1
APPENDIX C – SMAR WARRANTY CERTIFICATE	C.1



# INSTALLATION

# General

#### NOTE

The installation carried out in hazardous areas should follow the recommendations of the IEC60079-14 standard.

The overall accuracy of a flow, level, or pressure measurement depends on several variables. Although the transmitter has an outstanding performance, proper installation is essential to maximize its performance.

Among all factors, which may affect transmitter accuracy, environmental conditions are the most difficult to control. There are, however, ways of reducing the effects of temperature, humidity and vibration.

The **LD291** has a built-in temperature sensor to compensate for temperature variations. At the factory, each transmitter is submitted to a temperature cycle, and the characteristics under different temperatures are recorded in the transmitter memory. At the field, this feature minimizes the temperature variation effect.

# Mounting

Putting the transmitter in areas protected from extreme environmental changes can minimize temperature fluctuation effects.

In warm environments, the transmitter should be installed to avoid, as much as possible, direct exposure to the sun. Installation close to lines and vessels subjected to high temperatures should also be avoided. Use longer sections of impulse piping between tap and transmitter whenever the process fluid is at high temperatures. Use of sunshades or heat shields to protect the transmitter from external heat sources should be considered, if necessary.

Proper winterization (freeze protection) should be employed to prevent freezing within the measuring chamber, since this will result in an inoperative transmitter and could even damage the cell.

Although the transmitter is virtually insensitive to vibration, installation close to pumps, turbines or other vibrating equipment should be avoided.

The transmitter has been designed to be both rugged and lightweight at the same time. This make its mounting easier mounting positions are shown in Figure 1.1.

Should the process fluid contain solids in suspension, install valves or rod-out fittings at regular intervals to clean out the pipes.

The pipes should be internally cleaned by using steam or compressed air, or by draining the line with the process fluid, before such lines are connected to the transmitter (blow-down).

#### NOTE

When installing or storing the level transmitter, the diaphragm must be protected avoid scratchingdenting or perforation of its surface.

## LD291 - Operation and Maintenance Instruction Manual

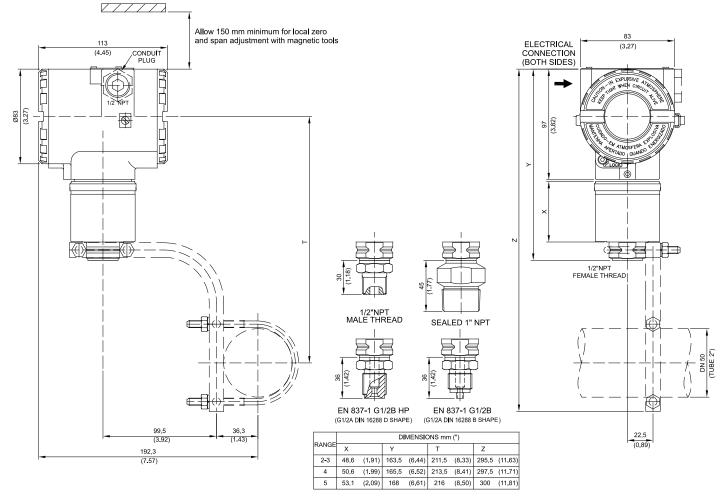
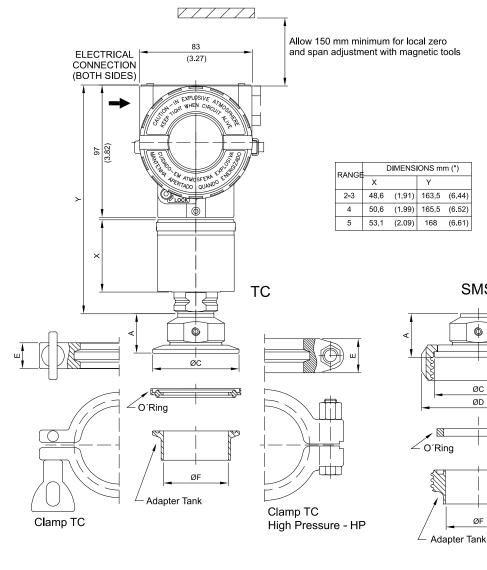


Figure 1.1(a) – Dimensional Drawing and Mounting Position for LD291



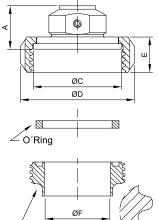
SMS

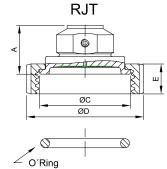
(6.52)

(6.61)

Υ

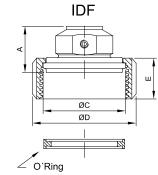
168

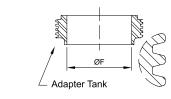


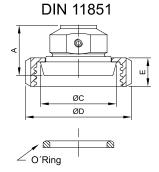


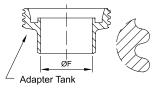
ØF

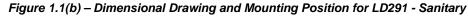
Adapter Tank





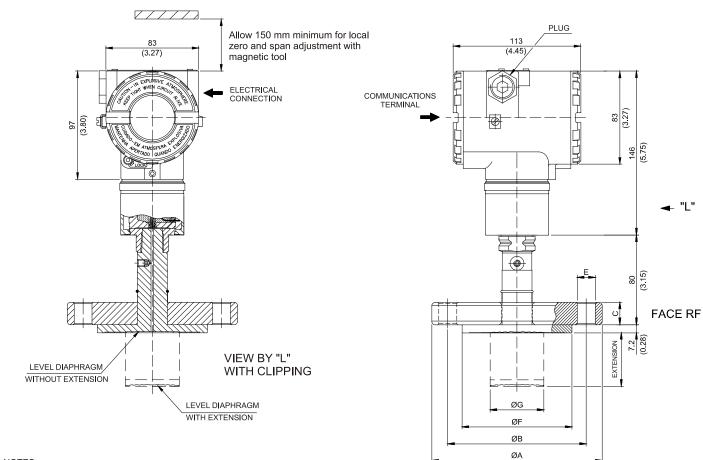






LD290S - CONNECTIONS					
		Dimens	ions in mm (ii	nche)	
CONNECTION	A	ØC	ØD	E	ØF
Tri-Clamp - 1 1/2" - wihtout extension	27 (1.06)	50 (1.96)	61 (2.40)	18 (0.71)	35 (1.38)
Tri-Clamp - 1 1/2" HP - without extension	27 (1.06)	50 (1.96)	66 (2.59)	25 (0.98)	35 (1.38)
Tri-Clamp - 2" - without extension	29 (1.14)	63,5 (2.50)	76,5 (3.01)	18 (0.71)	47,6 (1.87)
Tri-Clamp - 2" HP - without extension	29 (1.14)	63,5 (2.50)	81 (3.19)	25 (0.98)	47,6 (1.87)
Threaded DN40 - DIN 11851 - without extension	37 (1.46)	56 (2.20)	78 (3.07)	21 (0.83)	38 (1.50)
Threaded DN50 - DIN 11851 - without extension	38 (1.50)	68,5 (2.70)	92 (3.62)	22 (0.86)	50 (1.96)
Threaded SMS - 1 1/2" - without extension	31 (1.22)	55 (2.16)	74 (2.91)	25 (0.98)	35 (1.38)
Threaded SMS - 2" - without extension	32 (1.26)	65 (2.56)	84 (3.30)	26 (1.02)	48,6 (1.91)
Threaded RJT - 2" - without extension	35 (1.38)	66,7 (2.63)	86 (3.38)	22 (0.86)	47,6 (1.87)
Threaded IDF - 2" - without extension	34 (1.34)	60.5 (2.38)	76 (2.99)	30 (1.18)	47,6 (1.87)

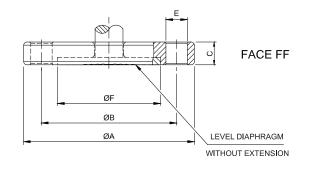
Figure 1.1(c) – Dimensional Drawing and Mounting Position for LD291 – Sanitary



NOTES:

-EXTENSION LENGHT mm (in): 0, 50 (1.96),	100 (3.93), 150	(5.9) OR 200 (7.87)
-DIMENSIONS ARE mm (in)		

	ANSI-B 16.5 DIMENSIONS							
DN	CLASS A				E	F (RF) (FF) G		HOLES
1"	150	108 (4.25)	79.4 (3.16)	14.3 (0.56)	16 (0.63)	50.8 (2)	-	4
'	300/600	124 (4.88)	88.9 (3.5)	17.5 (0.69)	19 (0.75)	50.8 (2)	-	4
	150	127 (5)	98.6 (3.88)	20 (0.78)	16 (0.63)	73.2 (2.88)	40 (1.57)	4
1.1/2"	300	155.4 (6.12)	114,3 (4.5)	21 (0.83)	22 (0.87)	73.2 (2.88)	40 (1.57)	4
	600	155.4 (6.12)	114,3 (4.5)	29,3 (1.15)	22 (0.87)	73.2 (2.88)	40 (1.57)	4
	150	152.4 (6)	120.7 (4.75)	17.5 (0.69)	19 (0.75)	92 (3.62)	48 (1.89)	4
2"	300	165.1 (6.5)	127 (5)	20.7 (0.8)	19 (0.75)	92 (3.62)	48 (1.89)	8
	600	165.1 (6.5)	127 (5)	25.4 (1)	19 (0.75)	92 (3.62)	48 (1.89)	8
	150	190.5 (7.5)	152.4 (6)	22.3 (0.87)	19 (0.75)	127 (5)	73 (2.87)	4
3"	300	209.5 (8.25)	168.1 (6.62)	27 (1.06)	22 (0.87)	127 (5)	73 (2.87)	8
	600	209.5 (8.25)	168.1 (6.62)	31.8 (1.25)	22 (0.87)	127 (5)	73 (2.87)	8
	150	228.6 (9)	190.5 (7.5)	22.3 (0.87)	19 (0.75)	158 (6.22)	89 (3.5)	8
4"	300	254 (10)	200 (7.87)	30.2 (1.18)	22 (0.87)	158 (6.22)	89 (3.5)	8
	600	273 (10.75)	215.9 (8.5)	38.1 (1.5)	25 (1)	158 (6.22)	89 (3.5)	8



			EN 109	2-1 / DIN250	D1 DIMEN	SIONS		
DN	PN	А	В	С	E	F	G	HOLES
25	10/40	115 (4.53)	85 (3.35)	18 (0.71)	14 (0.55)	68 (2.68)	-	4
40	10/40	150 (5.9)	110 (4.33)	20 (0.78)	18 (0.71)	88 (3.46)	40 (1.57)	4
50	10/40	165 (6.50)	125 (4.92)	20 (0.78)	18 (0.71)	102 (4.01)	48 (1.89)	4
80	10/40	200 (7.87)	160 (6.30)	24 (0.95)	18 (0.71)	138 (5.43)	73 (2.87)	8
100	10/16	220 (8.67)	180 (7.08)	20 (0.78)	18 (0.71)	158 (6.22)	89 (3.5)	8
100	25/40	235 (9.25)	190 (7.50)	24 (0.95)	22 (0.87)	162 (6.38)	89 (3.5)	8

Figure 1.1(d) – Dimensional Drawing and Mounting Position for LD291 – Level

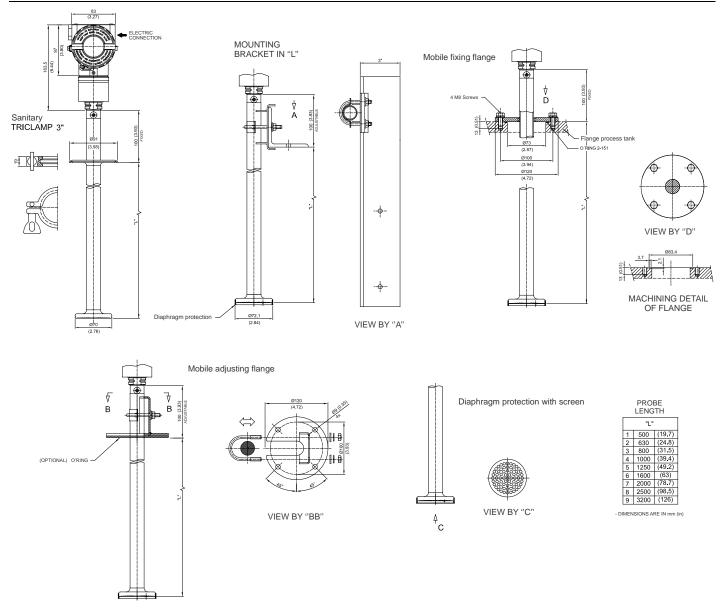


Figure 1.1 (e) – Dimensional Drawing and Mounting Position for LD291 – Level (Insertion)

The figure 1.2 shows how to use the tool to fix the process transmitter tap.

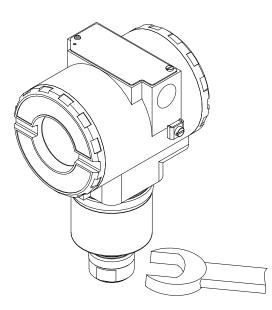


Figure 1.2 – Fixing of the Transmitter in the Tap

Observe operating safety rules during wiring, draining or blow-down.

	WARNING
	I safety precautions must be taken to avoid the possibility of an accident occurring when ng in conditions of high pressure and/or temperature.
Electric	cal shock can result in death or serious injury.
Avoid c	contact with the leads and terminals.
Proces	ss leaks could result in death or serious injury
Do not	attempt to loosen or remove flange bolts while the transmitter is in service.
•	ement equipment or spare parts not approved by Smar could reduce the pressure ng capabilities of the transmitter and may render the instrument dangerous.
Use on	ly bolts supplied or sold by Smar as spare parts.

shown in Figure 1.3.

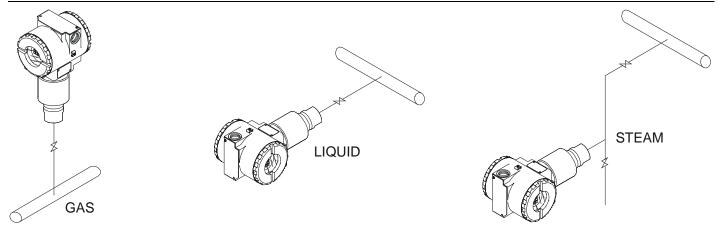
The location of pressure taps and the relative position of the transmitter are indicated in Table 1.1.

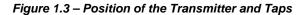
Process Fluid	Location of Taps	Location of LD291 in Relation to the Taps
Gas	Top or Side	Above the Taps.
Liquid	Side	Below the Taps or at the Piping Centerline.
Steam	Side	Below the Taps using Sealing (Condensate) Pots.

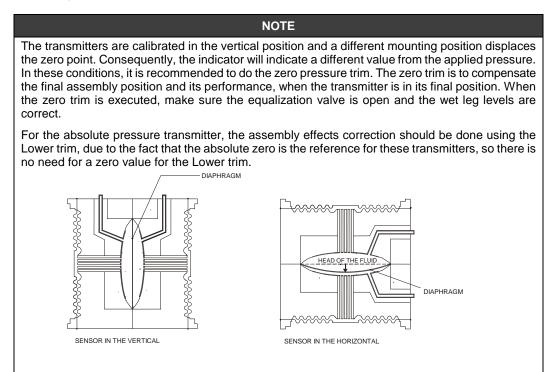
# Table 1.1 - Location of Pressure Taps

NOTE
Except for dry gases, all impulse lines should slope at the ratio 1:10, in order to avoid trapping bubbles in the case of liquids, or condensate for steam or wet gases.

### LD291 - Operation and Maintenance Instruction Manual







# **Electronic Housing**

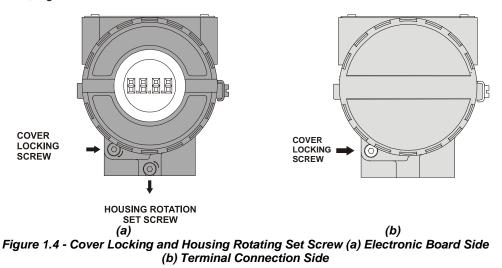
Humidity is fatal to electronic circuits. In areas subjected to high relative humidity, the O-rings for the electronic housing covers must be correctly placed and the covers must be completely closed by tighten them by hand until you feel the O-rings being compressed. Do not use tools to close the covers. Removal of the electronics cover in the field should be reduced to the minimum necessary, since each time it is removed; the circuits are exposed to the humidity.

The electronic circuit is protected by a humidity proof coating, but frequent exposures to humidity may affect the protection provided. It is also important to keep the covers tightened in place. Every time they are removed, the threads are exposed to corrosion, since painting cannot protect these parts. Code-approved sealing methods should be employed on conduit entering the transmitter.

# WARNING

The unused cable entries should be plugged and sealed accordingly to avoid humidity entering, which can cause the loss of the product's warranty.

The electronic housing can be rotated to adjust the digital display on a better position. To rotate it, loose the Housing Rotation Set Screw, see Figure 1.4 (a). To prevent humidity entering, the electric housing and the sensor joint must have a minimum of 6 fully engaged threads. The provided joint allows 1 extra turn to adjust the position of the display window by rotating the housing clockwise. If the thread reaches the end before the desired position, then rotate the housing counterclockwise, but not more than one thread turn. Transmitters have a stopper that restricts housing rotation to one turn. See Section 4, Figure 4.1.



Wiring

To release the cover that gives access to the wiring block, turn the cover locking screw clock wise, see the direction of the arrow in the figure 1.4.

**Test** and **Communication terminals** allow, respectively, to measure the current in the 4 - 20 mA loop, without opening it, and to communicate with the transmitter. To measure it, connect a multimeter in the mA scale in the "-" and "+" terminals, and to communicate, use a **HART** configurator in the "**COMM**" and "-" terminals. The wiring block has screws on which fork or ring-type terminals can be fastened. See Figure 1.6.

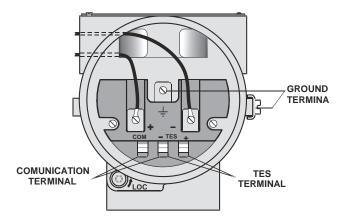


Figure 1.5– Wiring Block

The LD291 is protected against reverse polarity

For convenience there are two ground terminals: one inside the cover and one external, located close to the conduit entries.

Use of twisted pair (22 AWG or greater than) cables is recommended. Avoid routing signal wiring close to power cables or switching equipment.

The Figure 1.6 shows the correct installation of the conduit, to avoid penetration of water, or other substance, which may cause malfunctioning of the equipment.

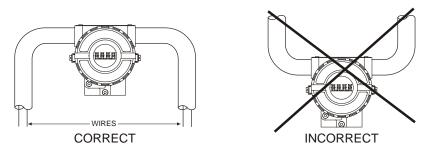


Figure 1.6 - Conduit Installation

# **Loop Conections**

Connection of the **LD291** should be done as in Figure 1.7. Connection in multi-drop configuration should be done as in Figure 1.8. Note that a maximum of 15 transmitters can be connected on the same line and that they should be connected in parallel.

Take care to the power supply as well, when many transmitters are connected on the same line. The current through the 250 Ohm resistor will be high causing a high voltage drop. Therefore make sure that the power supply voltage is sufficient.

The configuration can be connected to the communication terminals of the transmitter or at any point of the signal line by using the alligator clips. It is also recommended to ground the shield of shielded cables at only one end. The ungrounded end must be carefully isolated.

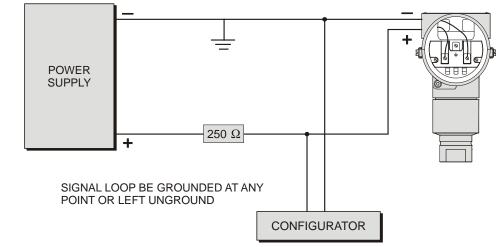


Figure 1.7 – Wiring Diagram for the LD291

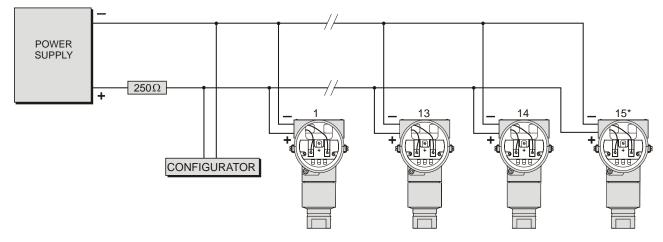


Figure 1.8 – Wiring Diagram for the LD291 in Multidrop Configuration

# NOTE

Make sure that the transmitter is operating within the operating area as shown on the load curve (Figure 1.9). Communication requires a minimum load of 250 Ohm.

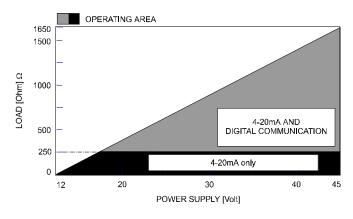


Figure 1.9 – Load Curve

# Installation in Hazardous Areas

WARNING
Explosions could result in death or serious injury, besides financial damage. Installation of this transmitter in explosive areas must be carried out in accordance with the local standards and the protection type adopted .Before continuing the installation make sure the certificate parameters are I n accordance with the classified area where the equipment will be installed.
The instrument modification or parts replacement supplied by other than authorized representative of Smar is prohibited and will void the certification.
The transmitters are marked with options of the protection type. The certification is valid only when the protection type is indicated by the user. Once a particular type of protection is selected, any other type of protection can not be used.
The electronic housing and the sensor installed in hazardous areas must have a minimum of 6 fully engaged threads. Lock the housing using the locking screw (Figure 1.4).

The cover must be tightened with at least 8 turns to avoid the penetration of humidity or corrosive gases. The cover must be tightened until it touches the housing. Then, tighten more 1/3 turn (120°) to guarantee the sealing. Lock the covers using the locking screw (Figure 1.4).

Consult the Appendix A for further information about certification.

# **Explosion/Flame Proof**

### WARNING

In Explosion-Proof installations the cable entries must be connected or closed using metal cable gland and metal blanking plug, both with at least IP66 and Ex-d certification.

As the transmitter is non-ignition capable under normal conditions, the statement "Seal not Required" could be applied for Explosion Proof Version (CSA Certification).

The standard plugs provided by Smar are certified according to the standards at FM. CSA and CEPEL. If the plug needs to be replaced, a certified plug must be used.

The electrical connection with NPT thread must use waterproofing sealant. A non-hardening silicone sealant is recommended.

Do not remove the transmitter covers when power is ON.

# Intrinsically Safe

# WARNING

In hazardous zones with intrinsically safe or non-incendive requirements, the circuit entity parameters and applicable installation procedures must be observed.

To protect the application the transmitter **must be connected to a barrier**. Match the parameters between barrier and the equipment (Consider the cable parameters). Associated apparatus ground bus shall be insulated from panels and mounting enclosures. Shield is optional. If used, be sure to insulate the end not grounded. Cable capacitance and inductance plus C<sub>i</sub> and L<sub>i</sub> must be smaller than Co and Lo of the associated Apparatus.

For free access to the Hart bus in the explosive environment, ensure the instruments in the loop are installed in accordance with intrinsically safe or non-incendive field wiring practices. Use only Ex Hart communicator approved according to the type of protection Ex-i (IS) or Ex-n (NI).

It is not recommended to remove the transmitter cover when the power is ON.

# **OPERATION**

# **Functional Description - Sensor**

The **LD291** Series Intelligent Pressure Transmitters uses capacitive sensors (capacitive cells) as pressure sensing elements, as shown in Figure 2.1.

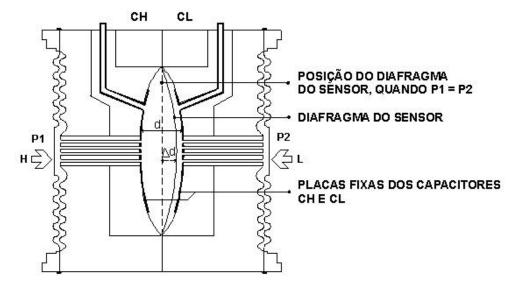


Figure 2.1 – Capacitive Cell

Where,

 $P_1$  and  $P_2$  are the pressures in chambers H and L

**CH=** capacitance between the fixed plate on P<sub>1</sub> side and the sensing diaphragm.

CL= capacitance between the fixed plate on the P<sub>2</sub> side and the sensing diaphragm.

d =distance between CH and CL fixed plates.

 $\Delta d$ = sensing diaphragm's deflection due to the differential pressure  $\Delta P = P_1 - P_2$ .

The capacitance of a capacitor with flat, parallel plates is a function expressed by plate area (A) and distance (d) between the plates as:

$$C \approx \frac{\varepsilon \times A}{d}$$

Where,

 $\mathcal{E}$  = dielectric constant of the medium between the capacitor's plates.

CH and CL are capacitances from flat parallel plates with identical areas, then:

$$CH \approx \frac{\varepsilon \times A}{(d/2) + \Delta d}$$
 and  $\frac{\varepsilon \times A}{(d/2) - \Delta d} \approx CL$ 

However, should the differential pressure ( $\Delta P$ ) be applied to the capacitive cell not deflect the sensing diaphragm beyond d/4, it is possible to assume  $\Delta P$  as proportional to  $\Delta d$ .

By developing the expression (CL - CH) / (CL + CH), it follows that:

$$\Delta P = \frac{CL - CH}{CL + CH} = \frac{2\Delta d}{d}$$

Because the distance (d) between the fixed plates CH and CL is constant, it is possible to conclude that the expression (CL - CH) / (CL + CH) is proportional to  $\Delta d$  and, therefore, to the differential pressure to be measured.

Thus it is possible to conclude that the capacitive cell is a pressure sensor formed by two capacitors whose capacitances vary according to the applied differential pressure.

# Functional Description - Hardware

Refer to the block diagram Figure 2.2. The function of each block is described below.

SENSOR

## MAIN BOARD

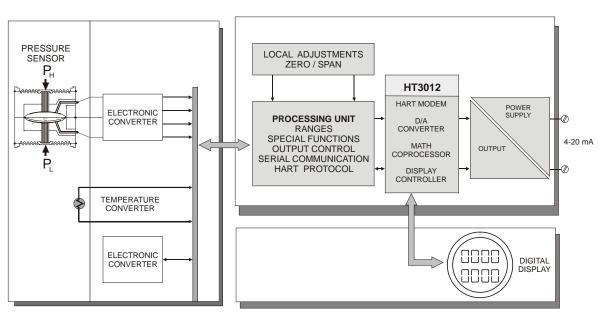


Figure 2.2 – LD291 Block Diagram Hardware

## Oscillator

This oscillator generates a frequency as a function of sensor capacitance.

### **Signal Isolator**

The Control signals from the CPU are transferred through optical couplers, and the signal from the oscillator is transferred through a transformer.

# (CPU) Central Processing Unit and PROM

The CPU is the intelligent portion of the transmitter, being responsible for the management and operation of all other blocks, linearization and communication.

The program is stored in an external PROM. For temporary storage of data, the CPU has an internal RAM. The data in the RAM is lost, if the power is switched off, however the CPU also has an internal nonvolatile EEPROM where data that must be retained is stored. Examples of such data are: calibration, configuration and identification data.

#### EEPROM

Another EEPROM is located within the sensor assembly. It contains data pertaining to the sensor's characteristics at different pressures and temperatures. This characterization is done for each sensor at the factory.

#### **D/A Converter**

Converts the digital data from the CPU to an analog signal with 14-bits resolution.

### Output

Control the current in the line feeding the transmitters. It acts as a variable resistive load whose value depends on the voltage from the D/A converter.

#### Modem

This system provider the data exchange between the serve-master digital communications. The transmitter demodulates serial information transmitted by the configurator from the current line, and after treating it, modulates the response sending it over the line. A "1" is represented by 1200 Hz and "0" by 2200 Hz. The frequency signal is symmetrical and does not affect the DC-level of the 4-20 mA signal.

### **Power Supply**

Power shall be supplied to the transmitter circuit using the signal line (2-wire system). The transmitter quiescent consumption is 3.6 mA; during operation, consumption may be as high as 21 mA, depending on the measurement and sensor status.

The **LD291** shows failure indication at 3.6 mA, if configured for low signal failure. At 21 mA, it will show the indication when configured for high signal failure. In case of low saturation, it will indicate failure at 3.6 mA and for high saturation, 21 mA, and measurements, proportional to the applied pressure in the range between 3.8 mA and 20.5 mA. 4 mA corresponds to 0% of the working range and 20 mA to100 % of the working range.

#### **Power Supply Isolation**

The sensor power supply is isolated from the main circuit by this module.

### **Display Controller**

It receives the data from the CPU and actives the LCD segments. Also it actives the back plane and the control signals for each segment.

#### Local Adjustment

Two switches magnetically activated. The magnetic tool without mechanical or electrical contact can activate them.

# Functional Description - Software

Refer to the Figure 2.3. The function of each Block is described below.

### **Factory Characterization**

Calculate the actual pressure from the capacitances and temperature readings obtained from the sensor using the factory characterization data stored in the sensor EEPROM.

#### **Digital Filter**

The digital filter is a low pass filter with an adjustable time constant. It is used to smooth noisy signals. The Damping value is the time required for the output reaching 63.2% for a step input of 100%.

#### **Customer Characterization**

The characterization TRIM points (P1 to P5) can be used to complement the transmitter's original characterization.

#### **Pressure Trim**

Here the values obtained by Zero Pressure TRIM and Upper Pressure TRIM corrects the transmitter for long term drift or the shift in zero or upper pressure reading due to installation or over pressure.

## Ranging

It used to set the pressure values corresponding to the output 4 and 20 mA. The LOWER-VALUE is the point corresponding to 4 mA, and UPPER-VALUE is the point corresponding to 20 mA.

### Function

Depending on the application, the transmitter output or controller PV may have the following characteristics according to the applied pressure: Linear (for pressure, and level measurement). The function is selected with FUNCTION.

#### **Customer Linearization**

This block relates the output (4-20 mA) to the input (applied pressure) according to a look-up table from 2 to 16 points.

The output is calculated by the interpolation of these points. The points are given in the function "TABLE POINTS" in percent of the range (Xi) and in percent of the output (Yi). It may be used to linearize, e.g., a level measurement to volume or mass. In flow measurement it can be used to correct for varying Reynolds number.

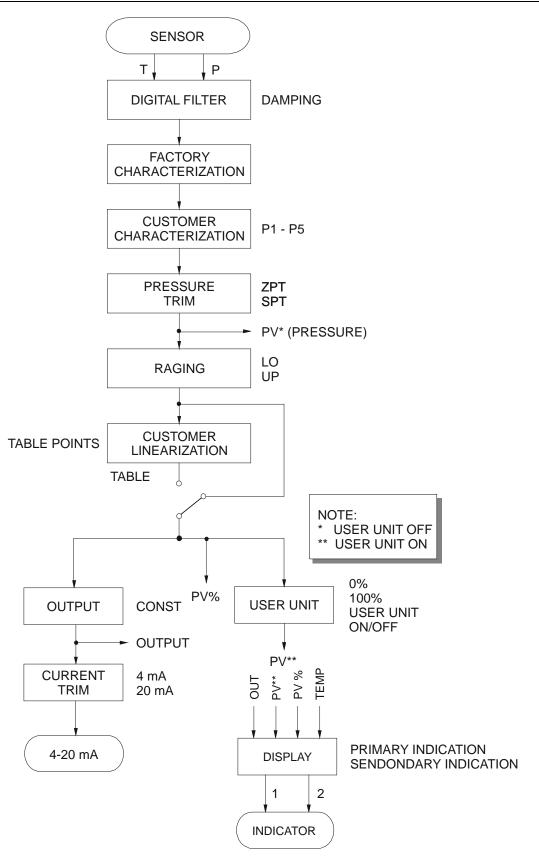


Figure 2.3 – LD291 – Software Block Diagram

### Output

Calculates the current proportional to the process variable or manipulated variable to be transmitted on the 4-20 mA output depending on the configuration in OP-MODE. This block also contains the constant current function configured in OUTPUT. The output is physically limited to 3.6 to 21 mA.

#### **Current Trim**

The 4 mA TRIM and 20 mA TRIM adjustment is used to make the transmitter current comply with a current standard, should a deviation arise.

### **User Unit**

Converts 0 and 100% of the process variable to a desired engineering unit read out available for the display and communication. It is used, e.g., to get a volume or from a level measurement, respectively. A unit for the variable can also be selected.

#### Display

Can alternate between two indications as configured in DISPLAY.

# The Display

The integral indicator is able to display one or two variables, which are user selectable. When two variables are chosen, the display will alternate between the two with an interval of 3 seconds.

The liquid crystal display includes a field with 4 1/2 numeric digits, a field with 5 alphanumeric digits and an information field, as shown on Figure 2.4.

### **DISPLAY V6.00**

The display controller, from release V6.00 on, is integral to the main board. Please observe the new spare parts codes.

#### Monitoring

During normal operation, the **LD291** is in the monitoring mode. In this mode, indication alternates between the primary and secondary variable as configured by the user. See Figure. 2.5. The display indicates engineering units, values and parameters simultaneously with most status indicators.

The monitoring mode is interrupted when the user does complete local adjustment.

The display is also capable of displaying an error and other messages (See table 2.1).

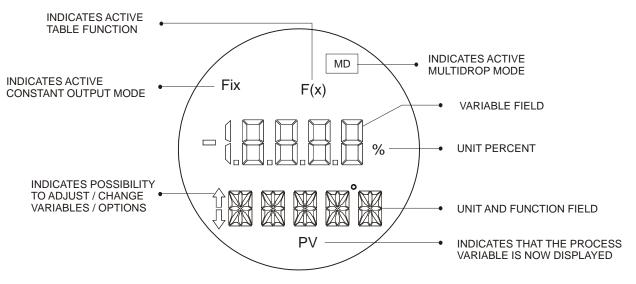


Figure 2.4 - Display

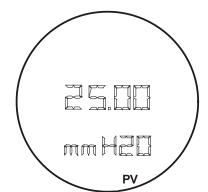


Figure 2.5 – Typical Monitoring Mode Display Showing PV, in this case 25.00 mmH<sub>2</sub>0

DISPLAY	DESCRIPTION			
INIT	The LD291 is in initializing after power on.			
CHAR	The LD291 is characterization mode. See Section 3 – Trim.			
FAIL SENS	Sensor failure. Refer to Section 5 - Maintenance.			
SAT	Current output saturated in 3.8 or 20.5 mA. See Section 5 – Maintenance.			

Table 2.1 - Display Messages

# CONFIGURATION

The **LD291** Intelligent Pressure Transmitter is a digital instrument with the most up-to-date features a measurement device can possibly have. Its digital communication protocol (HART<sup>®</sup>) enables the instrument to be connected to a computer in order to be configured in a very simple and complete way. Such computers connected to the transmitters are called HOST computers. They can either be Primary or Secondary Masters. Therefore, even the HART<sup>®</sup> being a master-slave type of protocol, it is possible to work with up to two masters in a bus. The Primary HOST plays the supervisory role and the Secondary HOST plays the Configurator role.

The transmitters may be connected in a point-to-point or multidrop type network. In a point-to-point connection, the equipment must be in its "0" address so that the output current may be modulated in 4 to 20 mA, as per the measurement. In a multidrop network, if the devices are recognized by their addresses, the transmitters shall be configured with a network address between "1" and "15. In this case, the transmitter's output current is kept constant, with a consumption of 4 mA each. If the acknowledgement mechanism is via Tag, the transmitter's addresses may be "0" while their output current is still being controlled, even in a multidrop configuration.

In the case of the **LD291 the** "0" address causes the **LD291** to control its output current and addresses "1" through "15" place the **LD291** in the multidrop mode with current control.

	NOTE					
			figuration for classified areas, the entity parameters allowed for Therefore, the following shall be checked:			
	С	a ≥ ∑ Ci <sub>j</sub> + Cc	$La \geq \Sigma Li_j + Lc$			
	V	oc <i>≤ min</i> [Vmax <sub>j</sub> ]	lsc ≤ min [lmax <sub>j</sub> ]			
Where:						
Ca, La	-	Barrier Allowable Capa	citance and Inductance			
Cij, Lij	-	Non protected internal (	Capacitance/Inductance of transmitter $j$ ( $j = 1$ up to 15)			
Cc, Lc	-	- Cable capacitance and Inductance				
V <sub>oc</sub>	-	- Barrier open circuit voltage				
I <sub>sc</sub>	- Barrier short circuit current					
Vmax <sub>j</sub>	- Maximum allowable voltage to be applied to the instrument <i>j</i>					
Imax <sub>j</sub>	-	Maximum allowable cur	rrent to be applied to the instrument <i>j</i>			

The **LD291** Intelligent Pressure Transmitter includes a very encompassing set of HART<sup>®</sup> Command functions that make it possible to access the functionality of what has been implemented. Such commands comply with the HART<sup>®</sup> protocol specifications, and are grouped as Overall Commands, Common Practice Controls Commands and Specific Commands. A detailed description of such commands may be found in the manual entitled HART<sup>®</sup> Command Specification - **LD291** Intelligent Pressure Transmitter.

Smar developed the **CONF401** and **HPC301** software, the first one works in Windows platform (**95**, **98**, **2000**, **XP** and **NT**) and **UNIX**. The second one, **HPC301**, works in the most recent technology in PDA's. They bring easy configuration and monitoring of field devices, capacity to analyze data and to modify the action of these devices. The operation characteristics and use of each one of the configurators are stated on their respective manuals.

Figures 3.1 and 3.2 show the front of the Palm and the CONF401 screen, with the active configuration.

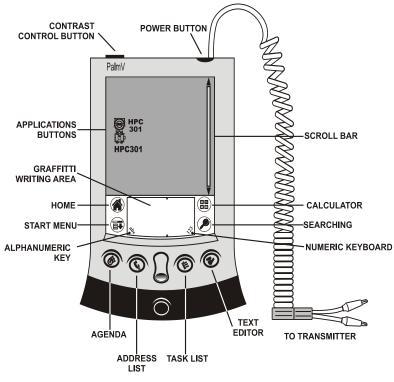


Figure 3.1 – Smar's Configurator

🔲 TAG - LD291								X				
LCD Indicator	Mainten	ance	Trim	Graphics	Multidrop	Fac	tory					
Device Status Ran			ange	Conf	iguration		Table User U					
Information Device Info				Datasheet	Info	Monite	onitor Specific Monitor					
	Write Pi Alarm Sele Fui		Linea		• •			Read Only Low				
				Sen	d							

Figure 3.2 – Screen of the Configurator

# **Configuration Features**

By means of the HART<sup>®</sup> Configurator, the **LD291** firmware allows the following configuration features to be accessed:

- Transmitter Identification and Manufacturing Data;
- Primary Variable Trim Pressure;
- ✓ Primary Variable Trim Current;
- Transmitter Adjustment to the Working Range;
- Engineering Unit Selection;
- ✓ Linearization Table;
- Device Configuration;
- Equipment Maintenance.

The operations, which take place between the configurator and the transmitter do not interrupt the Pressure measurement, and do not disturb the output signal. The configurator can be connected on the same pair of wires as the 4-20 mA signal, up to 2 km away from the transmitter.

# Manufacturing Data and Identification

The following information about the LD291 manufacturing and identification data is available:

TAG - 8 character alphanumeric field for identification of the transmitter;

**DESCRIPTOR** - 16 character alphanumeric field for additional identification of the transmitter. May be used to identify service or location;

**DATE** - The date may be used to identify a relevant date as the last calibration, the next calibration or the installation. The date is presented in the form of bytes where DD = [1,..31], MM = [1..12], AA = [0,..255], where the effective year is calculated by [Year = 1900 + AA];

**MESSAGE** - 32 character alphanumeric field for any other information, such as: the name of the person who made the last calibration, some special care to be taken, or if a ladder is needed for accessing;

INTEGRAL METER - Installed, Inert, Special, Unknown and None;

SENSOR FLUID\* - Silicone, Inert, Special, Unknown and None;

SENSOR ISOLATING DIAPHRAGM\* - 316 SST, Hastelloy C, Monel, Tantalum and Special;

SENSOR TYPE\* - It shows the sensor type;

**SENSOR RANGE\*** - It shows the sensor range in engineering units chosen by user. See Configuration Unit.

#### NOTE

Items marked with asterisk cannot be changed. They are read directly from the sensor memory.

# Primary Variable Trim - Pressure

Pressure, defined as a Primary Variable, is determined from the sensor readout by means of a conversion method. This method uses parameters obtained during the fabrication process. They depend on the electric and mechanical characteristics of the sensor, and on the temperature change to which the sensor is submitted. These parameters are recorded in the sensor's EEPROM memory. When the sensor is connected to the transmitter, such information is made available to the transmitter's microprocessor, which sets a relationship between the sensor signal and the measured pressure.

Sometimes, the pressure shown on the transmitter's display is different from the applied pressure. This may be due to several reasons, among which the following can be mentioned:

- ✓ The transmitter mounting position;
- ✓ The user's pressure standard differs from the factory standard;
- Sensor's original characteristics shifted by overpressure, over temperature or by long-term drift.

NOTE
Some users prefer to use this feature for zero elevation or suppression when the measurement refers to a certain point of the tank or tap (wet tap). Such practice, however, is not recommended when frequent laboratory calibrations are required, because the equipment adjustment refers to a relative measurement, and not to an absolute one, as per a specific pressure standard.

The Pressure Trim, as described on this document, is the method used in order to adjust the measurement as related to the applied pressure, as per the user's pressure standard. The most common discrepancy found in transmitters is usually due to Zero displacement. This may be corrected by means of the Zero Trim or the Lower Trim.

There are four types of pressure trim available:

LOWER TRIM: Is used to trim the reading at the lower range. The user informs to the transmitter the correct reading for the applied pressure via HART<sup>®</sup> configurator.

#### NOTE

Check on section 1, the note on the influence of the mounting position on the indicator. For better accuracy, the trim adjustment should be made in the lower and upper values of the operation range values.

✓ **UPPER TRIM:** Is used to trim the reading at the upper range. The user informs the transmitter the correct reading for the applied pressure via HART<sup>®</sup> configurator.

### ATTENTION

The upper pressure trim shall always be done after the zero trim.

- ZERO TRIM: is similar to the LOWER TRIM, but is assumed that the applied pressure is zero. The reading equal to zero must be active when the pressures of differential transmitter cameras are equalized or when a manometric transmitter opened to atmosphere or when the absolute transmitter is applied to the vacuum. Therefore, the user does not need to enter with any value.
- CHARACTERIZATION: this is used to correct an eventual non-linearity intrinsic to the conversion process. Characterization is done by means of a linearization table, with up to five points. The user shall apply pressure and use the HART<sup>®</sup> configurators to inform the pressure value applied to each point of the table. In most cases, characterization is not required, due to the efficiency of the fabrication procedure. The transmitter will display "CHAR", thus indicating that the characterization process is activated. The LD291 has a parameter to enable or disable the use of the Characterization Table.

## WARNING

The characterization trim changes the transmitter characteristics. Read the instructions carefully and certify that you are working with a pressure standard with accuracy 0.03% or better, otherwise the transmitter accuracy will be seriously affected.

# Primary Variable Current Trim

When the microprocessor generates a 0 % signal, the Digital to Analog converter and associated electronics are supposed to deliver a 4 mA output. If the signal is 100 %, the output should be 20 mA.

There might be differences between the Smar current standards and your plant current Standard. In this case, the Current Trim adjustment shall be used, with a precision Ammeter as measurement reference. Two Current Trim types are available:

- ✓ 4 mA TRIM: this is used to adjust the output current value corresponding to 0 % of the measurement;
- ✓ 20 mA TRIM: this is used to adjust the output current value corresponding to 100 % of the measurement.

The Current Trim shall be carried out as per the following procedure:

- Connect the transmitter to the precision Ammeter;
- Select one of the Trim types;
- ✓ Wait a moment for the current to stabilize and inform the transmitter the current readout of the precision Ammeter.

### NOTE

The transmitter presents a resolution that makes it possible to control currents as low as microamperes. Therefore, when informing the current readout to the transmitter, it is recommended that data input consider values up to tenth of microamperes.

# Transmitter Adjustment to the Working Range

This function directly affects the transmitter's 4-20 mA output. It is used to define the transmitter's working range; in this document it is referred to as the transmitter's calibration. The **LD291** transmitter includes two calibration features:

- CALIBRATION WITH REFERENCE: this is used to adjust the transmitter's working range, using a pressure standard as a reference.
- CALIBRATION WITHOUT REFERENCE: this is used to adjust the transmitter's working range, simply by having limit values informed by the user.

Both calibration methods define the Working Range Upper and Lower values, in reference to some applied pressure or simply informed by entered values. **CALIBRATION WITH REFERENCE** differs from the Pressure Trim, since **CALIBRATION WITH REFERENCE** establishes a relationship between the applied pressure and the 4 to 20 mA signal, and the Pressure Trim is used to correct the measurement value.

In the transmitter mode, the Lower Value always corresponds to 4 mA and the Upper Value to 20 mA. In the controller mode, the Lower Value corresponds to PV = 0 % and the Upper Value to PV = 100 %.

The calibration process calculates the **LOWER** and the **UPPER** values in a completely independent way. The adjustment of value does not affect the other. The following rules shall, however, be observed:

- ✓ The Lower and Upper values shall be within the range limited by the Minimum and maximum Ranges supported by the transmitter. As a tolerance, values exceeding such limits by up to 24 % are accepted, although with some accuracy degradation.
- The Working Range Span, determined by modulus of the difference between the Upper and Lower Values, shall be greater than the minimum span, defined by [Transmitter Range / 120]. Values up to 0.75 of the minimum span are acceptable with slight accuracy degradation.

#### NOTE

If the transmitter is operating with a very small span, it will be extremely sensitive to pressure variations. Keep in mind that the gain will be very high and any pressure change, no matter how small, will be amplified.

If it is necessary to perform a reverse calibration, that is, to work with an UPPER VALUE smaller than the LOWER VALUE, proceed as follows:

Place the Lower Limit in a value as far from the present Upper Value and from the new adjusted Upper value as possible, observing the minimum span allowed. Adjust the Upper Value at the desired point and, then, adjust the Lower Value.

This type of calibration is intended to prevent the calibration from reaching, at any moment, values not compatible with the range. For example: lower value equals to upper value or separated by a value smaller than the minimum span.

This calibration procedure is also recommended for zero suppression or elevation in those cases where the instrument installation results in a residual measurement in relation to a certain reference. This is the specific case of the wetted tap.

NOTE
In most applications with wetted taps, indication is usually expressed as a percentage. Should readout in engineering units with zero suppression be required, it is recommended to use the User Unit feature for such conversion.

# **Engineering Unit Selection**

Transmitter LD291 includes a selection of engineering units to be used in measurement indication.

For pressure measurements, the **LD291** includes an option list with the most common units. The internal reference unit is inH<sub>2</sub>O @ 20 °C; should the desired unit be other than this one, it will be automatically converted using conversion factors included in Table 3.1.

As the **LD291** uses a 4 ½ digit display, the largest indication will be 19999. Therefore, when selecting a unit, make sure that it will not require readouts greater than this limit. For User reference, Table 3.1 presents a list of recommended sensor ranges for each available unit.

CONVERSION FACTOR	NEW UNITS	RECOMMEND RANGE		
1.00000	Inches H <sub>2</sub> O at 20 <sup>o</sup> C	1, 2,3 & 4		
0.0734241	Inches Hg at 0 °C	all		
0.0833333	Feet H <sub>2</sub> O at 20 °C	all		
25.4000	Millimeters H <sub>2</sub> O at 20 °C	1&2		
1.86497	Millimeters Hg at 0 °C	1, 2, 3 & 4		
0.0360625	Pound/square inch - psi	2, 3, 4, 5 & 6		
0.00248642	Bar	3, 4, 5 & 6		
2.48642	Millibar	1, 2, 3 & 4		
2.53545	Gram/square centimeter	1, 2, 3 & 4		
0.00253545	kilogram/square centimeter	3, 4, 5 & 6		
248.642	Pascal	1		
0.248642	KiloPascal	1, 2, 3 & 4		
1.86497	Torr at 0 °C	1, 2, 3 & 4		
0.00245391	Atmosphere	3, 4, 5 & 6		
0.000248642	MegaPascal	4, 5 & 6		
0.998205	Inches of water at 4 °C	1, 2, 3 & 4		
25.3545	Millimeters of water at 4 $^{\circ}C$	1 & 2		

## Table 3.1 - Available Pressure Units

In applications where the **LD291** will be used to measure variables other than pressure or in the cases where a relative adjustment has been selected, the new unit may be displayed by means of the User Unit feature. This is the case of measurements such as level, volume, and flow rate or mass flow obtained indirectly from pressure measurements.

The User Unit is calculated taking the working range limits as a reference, which is, defining a value corresponding to 0% and another corresponding to 100% of the measurement:

- ✓ 0% Desired readout when the pressure is equal to the Lower Value (PV% = 0%, or transmitter mode output equal to 4 mA).
- ✓ **100%** Desired readout when the pressure is equal to the Upper Value (PV% = 100%, or transmitter mode output equal to 20 mA).

The user unit may be selected from a list of options included in the **LD291**. Table 3.2 makes it possible to associate the new measurement to the new unit so that all supervisory systems fitted with HART<sup>®</sup> protocol can access the special unit included in this table. The user will be responsible for the consistency of such information. The **LD291** cannot verify if the values corresponding to 0% and 100% included by the user are compatible with the selected unit.

VARIABLE	UNITS
Pressure	inH2O, InHg, ftH2O, mmH2O, mmHg, psi, bar ,mbar, g/cm <sup>2</sup> , kg/cm <sup>2</sup> , Pa, kPa, Torr, atm, MPa, in H2O <sup>4</sup> , mmH2O <sup>4</sup>
Volumetric Flow	ft <sup>3</sup> /min, gal/min, l/min, Gal/min, m <sup>3</sup> /h, gal/s, l/s, MI/d, ft <sup>3</sup> /s, ft <sup>3</sup> /d, m <sup>3</sup> /s, m <sup>3</sup> /d, Gal/h, Gal/d, ft <sup>3</sup> /h, m <sup>3</sup> /min, bbl/s, bbl/min, bbl/h, bbl/d, gal/h, Gal/s, l/h, gal/d
Velocity	ft/s, m/s, m/h
Volume	gal, liter, Gal, m <sup>3</sup> , bbl, bush, Yd <sup>3</sup> , ft <sup>3</sup> , In <sup>3</sup> , hl
Level	ft, m, in, cm, mm
Mass	gram, kg, Ton, lb, Sh ton, Lton
Mass Flow	g/s, g/min, g/h, kg/s, kg/min, kg/h, kg/d, Ton/min, Ton/h, Ton/d, lb/s, lb/min, lb/h, lb/d
Density	SGU, g/m <sup>3</sup> , kg/m <sup>3</sup> , g/ml, kg/l, g/l, Twad, Brix, Baum H, Baum L, API, % Solw, % Solv, Ball
Others	cSo, cPo, mA, %
special	5 characters

### Table 3.2 – Available User Units

Should a special unit other than those presented on Table 3.2 be required, the **LD291** allows the user to create a new unit by entering up to 5 alphanumeric digits.

The LD291 includes an internal feature to enable and disable the User Unit.

**Example**: transmitter **LD291** is connected to a horizontal cylindrical tank (6 meters long and 2 meters in diameter), linearized for volume measurement using camber table data in its linearization table. Measurement is done at the high-pressure tap and the transmitter is located 250 mm below the support base. The fluid to be measured is water at 20 °C. Tank volume is:  $[(\pi.d^2)/4].I = [(\pi.2^2)/4]\pi.6 = 18,85 \text{ m}^3$ .

The wet tap shall be subtracted from the measured pressure in order to obtain the tank level. Therefore, a calibration without reference shall be carried out, as follows:

In Calibration:

Lower =  $250 \text{ mmH}_2\text{O}$ Superior =  $2250 \text{ mmH}_2\text{O}$ Pressure unit =  $\text{mmH}_2\text{O}$ 

In User Unit:

User Unit 0% = 0User Unit  $100\% = 18.85 \text{ m}^3$ User Unit = m<sup>3</sup> When activating the User's Unit, **LD291** it will start to indicate the new measurement.

# Table Points

If the option TABLE is selected, the output will follow a curve given in the option TABLE POINTS. If you want to have your 4-20 mA proportional to the volume or mass of fluid inside a tank, you must transform the pressure measurement "X" into volume (or mass) "Y" using the tank strapping table, as shown in Table 3.3.

POINT	LEVEL (PRESSURE)	X	VOLUME	Y
1	-	-10%	-	-0.62%
2	250 mmH₂O	0%	0 m <sup>3</sup>	0%
3	450 mmH₂O	10%	0.98 m <sup>3</sup>	5.22%
4	750 mmH₂O	25%	2.90 m <sup>3</sup>	15.38%
5	957.2 mmH₂O	35.36%	4.71 m <sup>3</sup>	25%
6	1050 mmH₂O	40%	7.04 m <sup>3</sup>	37.36%
7	1150 mmH₂O	45%	8.23 m <sup>3</sup>	43.65%
8	1250 mmH <sub>2</sub> O	50%	9.42 m <sup>3</sup>	50%
15	2250 mmH₂O	100%	18.85 m <sup>3</sup>	100%
16	-	110%	-	106%

## Table 3.3 - Tank Strapping Table

As shown on the previous example, the points may be freely distributed for any desired value of X. In order to achieve a better linearization, the distribution should be concentrated in the less linear parts of the measurement.

The **LD291** includes an internal feature to enable and disable the Linearization Table.

# **Equipment Configuration**

The **LD291** enables the configuration of not only its operational services, but of instrument itself. This group includes services related to: Input Filter, Burn Out, Addressing, Display Indication and Passwords.

- ✓ **INPUT FILTER** The Input Filter, also referenced to as Damping, is a first class digital filter implemented by the firmware, where the time constant may be adjusted between 0 and 128 seconds. The transmitter's mechanical damping is 0.2 seconds.
- ✓ BURN OUT The output current may be programmed to go to the maximum limit of 21 mA (Full Scale) or to the minimum limit of 3.6 mA in case of transmitter failure. Configuring the BURNOUT parameter for Upper or Lower may do this.
- ✓ ADDRESSING The LD291 includes a variable parameter to define the equipment address in a HART<sup>®</sup> network. Addresses may go from value "0" to "15"; addresses from "1" to "15" are specific addresses for multidrop connections. This means that, in a multidrop configuration, the LD291 will display the message MDROP for addresses "1" to "15".

The LD291 is factory configured with address "0".

✓ DISPLAY INDICATION - the LD291 digital display is comprised of three distinct fields: an information field with icons indicating the active configuration status, a 4 ½ digit numeric field for values indication and a 5 digit alphanumeric field for units and status information.

The **LD291** may work with up to two display configurations to be alternately displayed at 2 second intervals. Parameters that may be selected for visualization are those listed on Table 3.4, below.

CURRENT	CURRENT IN MILIAMPÈRES							
CO	Analog Output Current in mA							
PR	Pressre in pressure unit.							
PV%	Process Variable in percentage.							
PV	Process Variable in engineering units.							
TE	Ambient temperature.							
	NONE - No variable on display (only LCD_2)							
ESC	Escape.							

## Table 3.4 - Variables for Display Indication

✓ WRITING PROTECTION - This feature is used to protect the transmitter configuration from changes via communication. All configuration data are writing protected.

The **LD291** include two write protection mechanisms: software and hardware locking; software locking has higher priority.

When the **LD291** writing software protection mechanism is enabled, it is possible, by means of specific commands, to enable or disable the write protection.

✓ PASSWORDS - this service enables the user to modify the operation passwords used in the LD291. Each password defines the access for a priority level (1 to 3); such configuration is stored in the LD291 EEPROM.

Password Level 3 is hierarchically upper to password level 2, which is upper to level 1.

# Equipment Maintenance

Here are grouped maintenance services related with the collection of information required for equipment maintenance. The following services are available: Order Code, Serial Number, Operation Counter and Backup/Restore.

✓ ORDER CODE - THE Order Code is the one used for purchasing the equipment, in accordance with the User specification. There are 13 characters available in the LD291 to define this code.

## EXAMPLE:

1	2	3	4	5	6	7	8	9	10	11	12	13
L	D	2	9	1	Μ	2	11	1	1	0	1	H1

**LD291 Intelligent Pressure Transmitter (D)**; Range: 1.25 to 50 kPa (2); Diaphragm of 316L SS, Silicone Oil Fill Fluid (1), and Connection to the process with 316L SS (11); with Digital Indicator (1); Electrical Connection 1/2 - 14 NPT (0); with Local Adjustment (1); with Carbon Steel Bracket and accessories (1); housing in SS (HI).

✓ **SERIAL NUMBER** - Three serial numbers are stored:

Circuit Number - This number is unique to every main circuit board and cannot be changed.

**Sensor Number** - The serial number of the sensor connected to the **LD291** and cannot be changed. This number is read from the sensor every time a new sensor is inserted in the main board.

Transmitter Number - the number that is written at the identification plate each transmitter.

NOTE
The transmitter number must be changed whenever there is the main plate change to avoid communication problems.

✓ OP\_COUNT - Every time a change is made, there is an increment in the respective change counter for each monitored variable, according to the following list. The counter is cyclic, from 0 to 255. The monitored items are:

LRV/URV: when any type of calibration is done;

**Function:** when any change in the transference function is done, e.g., linear, square root, const, table;

- Trim\_4mA: when the current trim is done at 4 mA;
- Trim\_20mA: when the current trim is done at 20 mA;
- Trim\_Zero/Lower: when pressure trim is done at Zero or Lower Pressure;
- Trim Upper Pressure: when the trim is done at Upper Pressure;

**Characterization:** when any change is made in any point of the pressure characterization table in trim mode;

**Multidrop:** when any change is made in the communication mode, for example, multidrop or single transmitter;

Pswd/C-Level: when any change is made in the password or the level configuration.

### ✓ BACKUP

When the main board is replaced, after assembling and powering it, the data saved in the sensor memory are automatically copied to the main board memory.

### ✓ RESTORE

This option allows copying or restoring the data saved in the sensor memory to the main board memory.

# PROGRAMMING USING LOCAL ADJUSTMENT

## The Magnetic Tool

Smar's magnetic tool is the second man machine interface. It comprises the advantage of the powerful HHT and the convenience of the magnetic tool.

If the transmitter is fitted with a display, and configured for Complete Local Adjustment (using the internal jumper), the magnetic tool is almost as powerful as the HHT. It eliminates the need for an HHT in most basic applications.

If the transmitter is not fitted with a display, or is configured for Simple Local Adjustment (using the internal jumper) the adjustment capability is reduced to ranging.

To select the function mode of the magnetic switches configures the jumpers located at the top of the main circuit board as indicated in Table 4.1.

SI/COM OFF/ON	NOTE	WRITE PROTECT	SIMPLE LOCAL ADJUSTMENT	COMPLETE LOCAL ADJUSTMENT
• • • • •		Disables	Disables	Disables
0 • • • • 0	1	Enables	Disables	Disables
• • • • • •	2	Disables	Enables	Disables
0 • • 0 • •		Disables	Disables	Enables

Notes: 1 - If the hardware protection is selected, the EEPROM will be protected.

2 - The local adjustment default condition is simple enabled and write protect disabled.

#### Table 4.1 – Local adjustment Selection

The transmitter has, under the identification plate, holes for two magnetic switches activated by the magnetic tool (See Figure 4.1).



Figure 4.1 – Local Zero and Span Adjustment and Local Adjustment Switches

The holes are marked with Z (Zero) and S (Span) and from now on will be designated simply by (Z) and (S), respectively. Table 4.2 shows the action performed by the magnetic tool while inserted in (Z) and (S) in accordance with the selected adjustment type.

Browsing the functions and their branches works as follows:

- Inserting the handle of the magnetic tool in (Z), the transmitter passes from the normal measurement state to the transmitter configuration state. The transmitter software automatically starts to display the available functions in a cyclic routine.
- 2. In order to reach the desired option, browse the options, wait until they are displayed and move the magnetic tool from (Z) to (S). Refer to Figure 4.2 Programming Tree Using Local Adjustment, in order to know the position of the desired option. By placing the magnetic tool once again in (Z), it is possible to browse for other options within this new branch.
- 3. The procedure to reach the desired option is similar to the one described on the previous item, for the whole hierarchical level of the programming tree.

Action	Simple Local Adjustment	Complete Local Adjustment	
Z	Selects the Lower Range Value Moves among all the options		
S	Selects the Upper Range Value	Activates the selected Functions	

Table 4.2 - Local A	djustment Description
---------------------	-----------------------

NOTE For LD291 versions prior to a V6.00, the digital display shall be number 214-0108 as per spare parts list for LD291 V6.XX.

For LD291 versions V6.XX, the digital display shall be number 400-0559, as per the updated spare parts list

### Simple Local Adjustment

The LD291 allows only the calibration of the values inferior and superior in this configuration.

### Zero and Span Reranging

The **LD291** can be very easily calibrated. It requires only Zero and Span adjustment in accordance with the working range.

The jumpers shall be configured for simple local adjustment. In case the **LD291** display is not connected, the simple local adjustment is automatically activated.

Zero calibration with reference shall be done as follows:

- ✓ Apply the Lower Value pressure.
- ✓ Wait for the pressure to stabilize.
- ✓ Insert the magnetic tool in the ZERO adjustment hole. (See Figure 4.1)
- ✓ Wait about 2 seconds. The transmitter should be reading 4 mA.
- ✓ Remove the tool.

Zero calibration with reference does not affect the span. In order to change the span, the following procedure shall be observed:

- ✓ Apply the Upper Value pressure.
- ✓ Wait for the pressure to stabilize.
- ✓ Insert the magnetic tool in the SPAN adjustment hole.
- Wait 2 seconds. The transmitter should be reading 20 mA.
- ✓ Remove the tool.

Zero adjustment causes zero elevation / suppression and a new upper value (URV) is calculated in accordance with the effective span. In case the resulting URV is higher than the Upper Limit Value (URL), the URV will be limited to the URL value, and the span will be automatically affected.

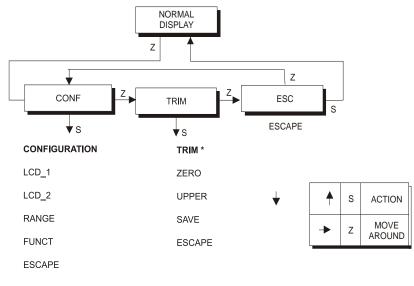
## Complete Local Adjustment

The transmitter must be fitted with the digital display for this function to be enabled. The following functions are available for local adjustment: Constant Current, Table Points Adjustment, User Units, and Fail-safe, Current Trim and Pressure, Address change and some items of function INFORMATION.

WARNING
When programming using local adjustment, the transmitter will not prompt, "Control loop should be
in manual!" as it does when programming using the HART® configurator. Therefore it is a good idea,
before configuration, to switch the loop to manual. And do not forget to return to auto after
configuration is completed.

## Local Programming Tree

The local adjustment uses a tree structure where, by placing the magnetic tool in (Z) it is possible to browse the options of a branch and by placing it in (S); details of the chosen option are shown. Figure 4.2 shows the LD291 available options.



\* PROTECTED BY A PASSWORD

THE PASSWORD CONSIST IN INSERT SCREWDRIVER HANDLE 2 TIMES IN THE "S" ORIFICE.

#### Figure 4.2 – Local Adjustment Programming Tree – Main Menu

**CONFIGURATION (CONF)** - Is the option where the output and display related parameters are configured: unit, primary and secondary display, calibration, and function.

**TRIM (TRIM)** – It is the option used to calibrate the "without reference" characterization and the digital reading.

**ESCAPE (ESC)** – It is the option used to go back to normal monitoring mode. The local adjustment is actived by actuation in **(Z)**.

## **Configuration** [CONF]

Configuration functions affect directly the 4-20 mA output current and the display indication. The configuration options implemented in this branch are the following:

- ✓ Selection of the variable to be shown on Display 1 and / or Display 2;
- Working range calibration of work. Options With and Without Reference are available;
- ✓ Digital filter damping time configuration of the readout signal input.
- Selection of the transference function to be applied to the measured variable.

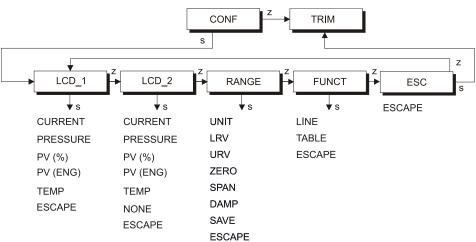
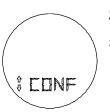


Figure 4.3 shows branch CONF with the available options.



## **Configuration Branch (CONF)**



Z: Moves to the TRIM branch.

S: Enters the CONFIGURATION branch, starting with function display (LCD\_1).

### Display 1 (LCD\_1)

Z: Moves to the function Display 2 (LCD\_2).



**S:** Starts selection of variable to be indicated as primary display.

After activating ( $\mathbf{S}$ ), you can move around the options available in the following table by activating ( $\mathbf{Z}$ ). See table 4.3.

The desired variable is activated using (S). Escape leaves primary variable unchanged.

Display 2 (LCD\_2)



Z: Moves to the RANGE function.

**S**: Starts selection of variable to be indicated as secondary display. The procedure for selection is the same as for LCD\_1, previous.

CURRENT	CURRENT IN MILIAMPÈRES
CO	Analog Output Current in mA
PR	Pressre in pressure unit.
PV%	Process Variable in percentage.
PV	Process Variable in engineering units.
TE	Ambient temperature.
	NONE - No variable on display (only LCD_2)
ESC	Escape.

Table 4.3 - Display Indication

## Range (RANGE)

Function Calibration (RANGE) presents the calibration options as a tree branch, as described on Figure 4.4.

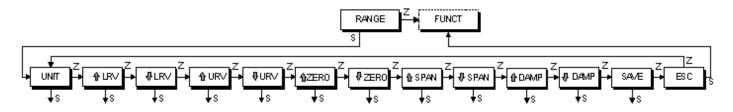


Figure 4.4 – Local Range Tree

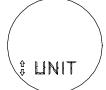
## Range Branch (RANGE)



**Z**: Moves to the FUNCT function from range branch.

S: Enters the RANGE branch, starting with the function UNIT.

Unit (UNIT)



Z: Moves to the LRV function.

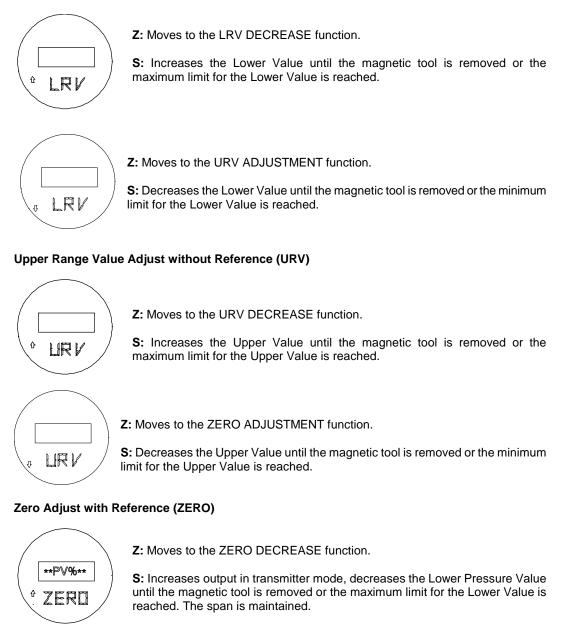
S: Starts selection of engineering unit for process variable. After activating (S), you can move around the options available in the table below by activating (Z). Using (S) activates the desired unit. Escape leaves the unit unchanged.

UNIT		
DISPLAY	DESCRIPTION	
InH <sub>2</sub> O	Inches water column at 20 °C	
InHg	Inches mercury column at 0 °C	
ftH <sub>2</sub> O	Feet water column at 20 °C	
mmH₂O	Millimeter water column at 20 °C	
mmHg	Millimeter mercury column at 0 °C	
psi	Pounds per square centimeter	
Bar	Bar	
Mbar	Millibar	
g/cm <sup>2</sup>	Grams per square centimeter	
k/cm <sup>2</sup>	Kilograms per square centimeter	
Pa	Pascals	
kPa	Kilo Pascals	
Torr*	Torr at 0 °C	
atm	Atmospheres	
ESC	Escape	

\* The Torr unit has been changed to mH<sub>2</sub>O@20 °C for version 6.04 or greater.

Table 4.4 – Units

#### Lower Range Value Adjustment without Reference (LRV)



Z: Moves to the SPAN ADJUSTMENT function.

**S:** Decreases Output in transmitter mode, increases the Lower Pressure Value until the magnetic tool is removed or the minimum limit for the Lower Value is reached. The span is maintained.

Span Adjust with Reference (SPAN)

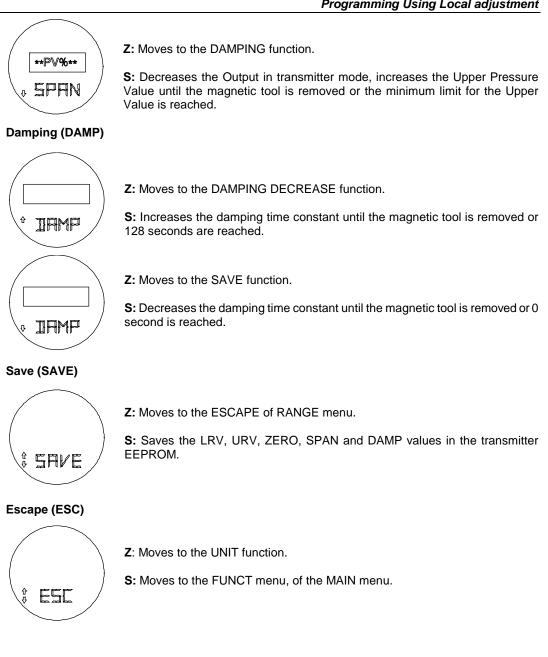


\*\*PV%\*\*

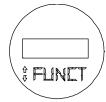
ZERO

**Z:** Moves to the SPAN DECREASE function.

**S**: Increases the Output in transmitter mode, decreases the Upper Pressure Value until the magnetic tool is removed or the maximum limit for the Upper Value is reached.



## Function (FUNCT)



Z: Moves to the ESCAPE function.

S: Starts selection of input function. After activating (S) you can move around the available options in the table below by activating (Z).

FUNCTIONS		
DISPLAY	DESCRIPTION	
LINE	Linear to Pressure.	
TABLE	16 Point Table.	
ESC	ESC to Escape from the superior Branch.	

#### Table 4.5 – Functions

The desired function is activated using (**S**). Escape leaves function unchanged.



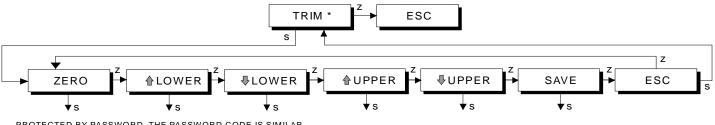
Z: Recycles for menu LCD – 1.

S: Moves to the CONF function of the main menu.

## Pressure Trim [TRIM]

This field of the tree is used to adjust the digital reading according to the applied pressure. The pressure TRIM differs from RANGING WITH REFERENCE, since the TRIM is used to correct the measure and RANGING WITH REFERENCE reach only the applied pressure with the output signal of 4 to 20 mA.

Figure 4.5 shows the options available to run the pressure TRIM.



PROTECTED BY PASSWORD. THE PASSWORD CODE IS SIMILAR THAT DESCRIBED FOR THE OPERATION (MODE), IN THE PAGE 4.11.

Figure 4.5 – Pressure Trim Tree

#### Trim Branch (TRIM)



**Z:** Moves to ESC function.

**S:** These functions are protected by a "password." When prompted PSWD activates (**S**) 2 times to proceed. After entering the password, the TRIM branch starting with the Zero Trim function is accessed.

#### NOTE

Check on section 1, the note on the influence of the mounting position on the indicator. For better accuracy, the trim adjustment should be made in the lower and upper values of the operation range values.

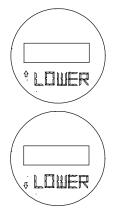
#### Zero Pressure Trim (ZERO)



**Z:** Moves to the LOWER pressure TRIM function.

S: Trims the transmitters' internal reference to read 0 at the applied pressure.

#### Lower Pressure Trim (LOWER)



Z: Moves to option DECREASES THE LOWER PRESSURE VALUE.

S: Adjusts the transmitter's internal reference, increasing the displayed value that will be interpreted as the Lower Pressure value corresponding to the applied pressure.

**Z**: Moves on to function SAVE if the Lower Pressure Trim (LOWER) is running or to the Upper Pressure Trim (UPPER).

**S:** Adjusts the transmitter's internal reference, decreasing the displayed value that will be interpreted as the Lower Pressure value corresponding to the applied pressure.

#### Upper Pressure Trim (UPPER)



Z: Moves to the decrease Upper Pressure reading.

**S:** Sets the transmitters' internal reference increasing to the value on the display, which is the reading of the applied pressure.

Z: Moves to the SAVE function.

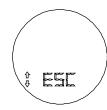
**S**: Sets the transmitters' internal reference decreasing to the value on the display, which is the reading of the applied pressure.



Z: Moves to the ESCAPE from TRIM menu.

**S:** Saves the LOWER and UPPER TRIM point in the transmitter EEPROM and actualize the internal parameters pressure measurement.

#### Escape (ESC)

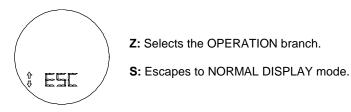


Z: Moves to the ZERO TRIM function.

S: Escapes to the MAIN menu.

## Escape Local Adjustment [ESC]

This branch of the main tree is used to leave the Local Adjustment mode, placing the Transmitter or Controller in the monitoring mode.



# **MAINTENANCE PROCEDURES**

### General

NOTE

Equipments installed in hazardous atmospheres must be inspected in compliance with the IEC60079-17 standard.

**SMAR LD291** intelligent pressure transmitters are extensively tested and inspected before delivery to the end user. Nevertheless, its design includes additional information for diagnosis purposes, in order to provide an easier fault detection capability and, as a consequence, an easier maintenance.

In general, it is recommended that end users do not try to repair printed circuit boards. Spare circuit boards may be ordered from **SMAR** whenever necessary.

The sensor has been designed to operate for many years without malfunctions. Should the process application require periodic cleaning of the transmitter, the flanges may be easily removed and reinstalled.

Should the sensor eventually require maintenance, it may not be changed in the field. In this case, the possibly damaged sensor should be returned to **SMAR** for evaluation and, if necessary, repair. Refer to the item "Returning Materials" at the end of this Section.

## Diagnostic with the Configurator

Should any problem be noticed relating to the transmitter output, the configurator may carry out investigation, as long as power is supplied and communication and the processing unit are operating normally (see Table 5.1).

The configurator should be connected to the transmitter according to the wiring diagram shown on Section 1, Figures 1.10 and 1.11.

### Error Messages

When communicating using the CONFIGURATOR the user will be informed about any problem found by the transmitter self-diagnostics.

Table 5.1 presents a list of error messages with details for corrective actions that may be necessary.

ERROR MESSAGES	POTENTIAL SOURCE OF PROBLEM		
UART RECEIVER FAILURE:	The line resistance is not according to load curve.		
PARITY ERROR	Excessive noise or ripple in the line.		
OVERRUN ERROR	Low level signal.		
ERROR CHECK SUM	Interface damaged.		
FRAMING ERROR	Power supply with inadequate voltage.		
	<ul> <li>Transmitter line resistance is not according to load curve;</li> </ul>		
	Transmitter not powered;		
CONFIGURATOR RECEIVES NO	<ul> <li>Interface not connected or damaged;</li> </ul>		
ANSWER FROM TRANSMITTER	Repeated bus address;		
	<ul> <li>Transmitter polarity is reversed;</li> </ul>		
	Interface damaged;		
	<ul> <li>Power supply with inadequate voltage.</li> </ul>		
	<ul> <li>Software version not compatible between configurator and transmitter.</li> </ul>		
CMD NOT IMPLEMENTED	Configurator is trying to carry out a <b>LD291</b> specific command in a transmitter from another manufacturer.		
TRANSMITTER BUSY	Transmitter carrying out an important task, e.g., local adjustment.		
XMTR MALFUNCTION	Sensor disconnected.		
	Sensor failure.		

ERROR MESSAGES	POTENTIAL SOURCE OF PROBLEM		
COLD START	Start-up or Reset due to power supplies failure.		
OUTPUT FIXED	Output in Constant Mode.		
OUTPUT FIXED	Transmitter in Multidrop mode.		
OUTPUT SATURATED	• Pressure out of calibrated Span or in fail-safe state (Output current in 3.8 or 20.5 mA).		
SV OUT OF LIMITS	Temperature out of operating limits.		
	Temperature sensor damaged.		
	Pressure out of operation limits.		
PV OUT OF LIMITS	<ul> <li>Sensor damaged or sensor module not connected.</li> </ul>		
	Transmitter with false configuration.		
LOWER RANGE VALUE TOO HIGH	<ul> <li>Lower value exceeds 24% of the Upper Range Limit.</li> </ul>		
LOWER RANGE VALUE TOO LOW	• Lower value exceeds 24% of the Lower Range Limit.		
UPPER RANGE VALUE TOO HIGH	Upper value exceeds 24% of the Upper Range Limit.		
UPPER RANGE VALUE TOO LOW	Upper value exceeds 24% of the Lower Range Limit.		
UPPER & LOWER RANGE VALUES OUT OF LIMITS	<ul> <li>Lower and Upper Values are out of the sensor range limits.</li> </ul>		
SPAN TOO SMALL	• The difference, between the Lower and Upper values is less than the 0.75 x (minimum span).		
APPLIED PRESURE TOO HIGH	The pressure applied was above the 24% upper range limit.		
APPLIED PRESURE TOO LOW	The pressure applied was below the 24% lower range limit.		
EXCESS CORRECTION	• The trim value entered exceeded the factory-characterized value by more than 10%.		
PASSED PARAMETER TOO LARGE	Parameter above operating limits.		
PASSED PARAMETER TOO SMALL	Parameter below operating limits.		

Table 5.1 - Error Messages and Potential Source

## Diagnostic with the Transmitter

#### Symptom: NO LINE CURRENT

Probable Source of Trouble:

- ✓ Transmitter Connections
  - Check wiring polarity and continuity;
  - Check for shorts or ground loops;
  - Check if the power supply connector is connected to main board.

#### ✓ Power Supply

- Check power supply output. The voltage must be between 12 and 45 Vdc at transmitter terminals.
- ✓ Electronic Circuit Failure
  - Check the main board for defect by using a spare one.

#### Symptom: NO COMMUNICATION

#### Probable Source of Trouble:

Terminal Connections

- Check the terminal interface connection of the configurator.
- Check if the interface is connected to the wires leading to the transmitter or to the terminals [+] and [-].
- Check if the interface is models IF3 (for Hart protocol).

#### Transmitter Connections

- Check if connections are according to wiring diagram.
- Check if there is resistance in the 250  $\Omega$  line.

#### ✓ Power Supply

Check output of power supply. The voltage at the LD291 terminals must be between 12 and 45 Vdc, and ripple less than 500 mV.

#### ✓ Electronic Circuit Failure

- Locate the failure by alternately testing the transmitter circuit and the interface with spare parts.
- Transmitter Address
  - Check if the transmitter address is compatible with the one expected by the configurator.

#### Symptom: CURRENT OF 21.0 mA or 3.6 mA

#### **Probable Source of Trouble:**

- Pressure Tap (Piping)
  - Verify if blocking valves are fully open;
  - Check for gas in liquid lines or for liquid in dry lines;
  - Check the specific gravity of process fluid;
  - Check process flanges for sediments;
  - Check the pressure connection;
  - Check if bypass valves are closed;
  - Check if pressure applied is not over upper limit of transmitter's range.

#### **Sensor to Main Circuit Connection**

• Check connection (male and female connectors).

#### Electronic Circuit Failure

- Check the sensor circuit for damage by replacing it with a spare one.
- Replace sensor.

#### Symptom: INCORRECT OUTPUT

#### Probable Source of Trouble:

#### Transmitter Connections

- Check power supply voltage.
- Check for intermittent short circuits, open circuits and grounding problems.

#### Noise Measurement Fluid

- Adjust damping
- ✓ Pressure Tap
  - Check for gas in liquid lines and for liquid in steam or gases lines.
  - Check the integrity of the circuit by replacing it with a spare one.

#### Calibration

• Check calibration of the transmitter.

NOTE

A 21.0 or 3.6 mA current indicates that the transmitter is in Burnout (TRM) or safety output. Use the configurator to investigate the source of the problem.

#### Symptom: DISPLAY INDICATES "FAIL SENS"

#### Probable Error Source:

- Sensor Connection to the Main Board Check the connection (flat cable, male and female connectors).
- Type of Sensor Connected to the Main Board Check if the sensor connected to the main board is the one specified for the LD291 model: sensor type shall be hyper - High Performance.
- ✓ Electronic Circuit Failure

Check if the sensor set is damaged, replacing it for a spare one.

### **Disassembly Procedure**

	WARNING
Do not disassemble with power on.	

Figure 5.3 shows transmitter's exploded view and will help you to visualize the following:

#### SENSOR

In order to have access to the sensor (18) for cleaning purposes, the transmitter should be removed from its process connections.

Loosen the hex screw (8) and carefully unscrew the electronic housing from the sensor, observing that the flat cable is not excessively twisted.

#### WARNING

To avoid damage do not rotate the electronic housing more than 270° starting from the fully threaded without disconnecting the electronic circuit from the sensor and from the power supply. See Figure 5.1.



Figure 5.1 – Safety Housing Rotation

#### **ELECTRONIC CIRCUIT**

To remove the circuit board (6), loosen the two screws (5) that anchor the board and hold the (7) spacers in the other side to avoid losing them.

#### WARNING

The board has CMOS components, which may be damaged by electrostatic discharges. Observe correct procedures for handling CMOS components. It is also recommended to store the circuit boards in electrostatic-proof cases.

Pull the main board out of the housing and disconnect the power supply and the sensor connectors.

WARNING

### Reassembly Procedure

Do not assemble with power on.

#### SENSOR

When mounting the sensor (18), it is recommended to make use of a new set of gaskets (17) compatible with the process fluid.

O'rings should be lightly lubricated with silicone oil before they are fitted into their recesses. Use halogen grease for inert fill applications.

The fitting of the sensor must be done with the main board out of the electronic housing. Mount the sensor to the housing turning it clockwise until it stops. Tighten the screw (8) to lock the body to the sensor.

#### **ELECTRONIC CIRCUIT**

Plug sensor connector and power supply connector to main board. If there is a display, attach it to the main board by means of 4 screws (3). The display can be installed in any of the 4 possible positions (See Figure 5.2).

The " $\blacktriangle$ " mark indicates up position.

Pass the screws (5) through the main board holes (6) and the spacers (7) as shown on Figure 5.3 and tighten them to the body.

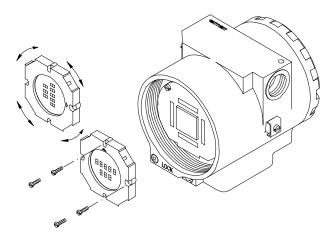


Figure 5.2 – Four Possible Positions of the Display

After tightening the protective cover (1), mounting procedure is complete. The transmitter is ready to be energized and tested. It is recommended that adjustment be done on the ZERO TRIM and on the UPPER PRESSURE TRIM.

### Interchangeability

In order to obtain an accurate and better temperature compensated response, each sensor is submitted to a characterization process and the specific data is stored in an EEPROM located in the sensor body.

The main board, in this operation, reads the sensor serial number and compares it with the number stored in the main board. In case they do not match, the circuit considers that the sensor has been changed and will probe the memory of the new sensor for the following information:

- ✓ Temperature compensation coefficients;
- ✓ Sensor trim data, including 5-point characterization curve;
- ✓ Sensor characteristics: type, range, diaphragm material and fill fluid.

Information not transferred during sensor replacement will remain unchanged in the main board memory. Thus, information such as Upper Value, Lower Value, Damping, Pressure Unit and replaceable transmitter parts (Flange, O-ring, etc.) shall be updated, depending whether the correct information is that of the sensor or the main board. In the case of a new sensor, the main board will have the most updated information about the process; in the opposite case, the sensor will have it. Depending on the situation, the updating shall be from one or the other.

Data transference from the main board to the sensor or vice versa, can also be forced by function BACKUP/RESTORE from sensor.

### **Returning Materials**

Should it become necessary to return the transmitter and/or configurator to **SMAR**, simply contact our office, informing the defective instrument serial number, and return it to our factory.

If it becomes necessary to return the transmitter and/or configurator to Smar, simply contact our office, informing the defective instrument's serial number, and return it to our factory. In order to speed up analysis and solution of the problem, the defective item should be returned with the Service Request Form (SRF – Appendix B) properly filled with a description of the failure observed and with as much details as possible. Other information concerning to the instrument operation, such as service and process conditions, is also helpful.

Instruments returned or to be revised outside the guarantee term should be accompanied by a purchase order or a quote request.

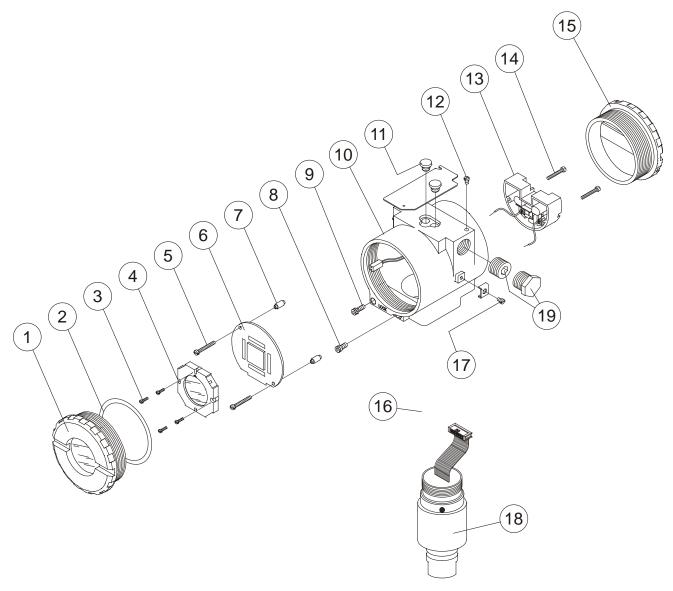


Figure 5.1 – Exploded View

ACCESSORIES			
ORDERING CODE	DESCRIPTION		
SD-1	Magnetic Tool for local adjustment.		
Palm	8 Mbytes Palm Handheld, including installation and initialization software for the HPC301.		
HPC301-SF1-V	HART <sup>®</sup> Interface HPI311-V for Palm, including the configuration package for Smar transmitters and for third parties transmitters.		
HPI311-V	HART <sup>®</sup> interface.		

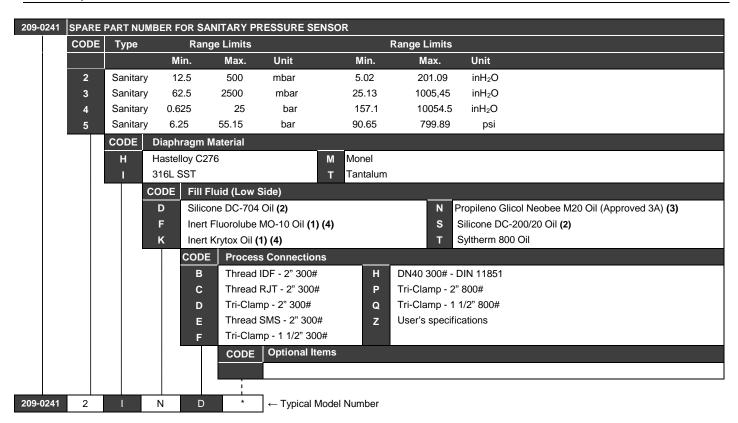
SPARE PARTS LIST FOR TRANSMITTER				
DES	CRIPTION OF PARTS	POSITION	CODE	CATEGORY (NOTE 1)
HOUSING, Aluminum ( <b>NOTE 2</b> )	. 1/2 - 14 NPT	10	209-0240	
	. M20 x 1.5	10	209-0241	
	. PG 13.5 DIN	10	209-0242	
	. 1/2 - 14 NPT	10	209-0243	
HOUSING, 316 Stainless Steel (NOTE 2)	. M20 x 1.5	10	209-0244	
	. PG 13.5 DIN	10	209-0245	
	. Aluminum	1 and 15	204-0102	
COVER (Includes O-ring)	. Stainless Steel 316	1 and 15	204-0105	
COVER WITH WINDOW FOR INDICATOR	. Aluminum	1	204-0103	
(Includes O-ring)	. Stainless Steel 316	1	204-0106	
COVER LOCKING SCREW.		9	204-0120	
SENSOR LOCKING SCREW.	. Without Head M6 Screw	8	400-1121	
EXTERNAL GROUND SCREW.		17	204-0124	
IDENTIFICATION PLATE FIXING SCREW.		12	204-0116	
DISPLAY (Included Screws).		3 and 4	400-0559	
TERMINAL BLOCK ISOLATOR.		13	400-0058	
MAIN BOARD (Display and mounting Kit Inclu	ided ) GLL 1071.	6	400-0610	А
MAIN BOARD (Display and Mounting Kit not I	ncluded ) – GLL 1071.	6	400-0572	А
MAN BOARD with Mounting Kit and without di	splay - GLL 1071.	6	400-0609	A
MAIN FIXATION BOARD KIT (Screws and Spa	icers).	5 and 7	400-0560	
O-RINGS ( <b>NOTE 3</b> ).	. Cover, BUNA-N.	2	204-0122	В
O-RINGS (NOTE 3).	. Neck, BUNA-N.	16	204-0113	В
	. HOUSING, Aluminum.	14	304-0119	
TERMINAL HOLDING SCREW.	. HOUSING, 316 SS.	14	204-0119	
MAIN BOARD SCREW HOUSING IN	.Units without indicator.	3	304-0118	
ALUMINUM.	.Units with indicator.	3	304-0117	
MAIN BOARD SCREW HOUSING IN 316	.Units with indicator.	3	204-0118	
STAINLESS STEEL.	.Units without indicator.	3	204-0117	
	. Carbon Steel.	-	209-0801	
MOUNTING BRACKET FOR 2" PIPE MOUNTING ( <b>NOTE 5</b> ).	. Stainless Steel 316.	-	209-0802	
	. Carbon Steel with bolts, nuts, washers and U-clamp in 316SS.	-	209-0803	
LOCAL ADJUSTMENT PROTECTION CAP.		11	204-0114	
SENSOR.		18	(NOTA 4)	В
PLUG	1/2 NPT Internal Hexagon Plug in Plated CS BR Ex d. 1/2 NPT Internal Hexagon Plug in 304 SST BR Ex d. M20 X 1.5 External Hexagon Plug in 316 SST BR Ex d.	19 19 19	400-0808 400-0809 400-0810	
	PG13.5 External Hexagon Plug in 316 SST BR Ex d.	19	400-0811	

Note: 1) for category A, it is recommended to keep, in stock, 25 parts installed for each set, and 50 for category B.
2) Include Terminal Block, Screws, caps, and Identification plate without certification.
3) O-rings and Backup Rings are packaged in packs of 12 units, except for spring loaded.
4) To specify sensors, use the following tables.
5) Including U-Clamp, nuts, bolts and washers

## Ordering Code for Sensor

CODE	Е Туре	Ra	inge Limits			Range Limits						
		Min.	Max.	Unit	Min.	Max.	Unit					
M2	Gage	12.5	500	mbar	5.02	201.09	$inH_2O$					
M3	Gage	62.5	2500	mbar	25.13	1005.45	inH₂O					
M4	Gage	0.625	25	bar	157.1	10054.5	$inH_2O$					
M5	Gage	6.25	250	bar	90.65	3625.94	psi					
ł	CODE	Diaphrag	m Material a	nd Fill Fluid								
	1	316L SST -	Silicone Oil		E	Hastelloy C2	276 – Inert	Krytox Oil (2)				
- i	2	316L SST -	- Inert Fluoro	lube Oil <b>(2)</b>	Q	316L SST –	Inert Halo	carbon 4.2 Oil <b>(2)</b>				
Ì	3	Hastelloy C	276 - Silicor	e Oil <b>(1)</b>	R	R Hastelloy C276 – Inert Halocarbon 4.2 Oil (2)						
	4	Hastelloy C	276 – Inert F	luorolube Oil (2)	Z	User's speci	fications					
-	D	316L SST -	<ul> <li>Inert Krytox</li> </ul>	: Oil <b>(2)</b>								
÷		CODE P	rocess Con	nections Materia	l							
Ì		H Ha	astelloy C27	6 <b>(1)</b>	I 316	L SST		Z User's specifications				
		C	ODE Pro	cess Connection	ıs							
-	1		1 1/2 -	14 NPT - Female			U 1/2	BSP – Male				
			A M20	X 1.5 Male				ve Manifold integrated to the transmitter				
į.	i		G G 1/2	2 A DIN 16288 - F	orm B <b>(3)</b>			IPT Sealed				
				2 DIN 16288 - Fori	m D <b>(3)</b>		z <sup>Use</sup>	r's specifications				
			M 1/2 -	14 NPT - Male								
M2	1	I	А			← 1	Typical Mo	del Number				

(2) Inert Fluid: safe for oxygen service.(3) The DIN 16288 standards was substituted by the DIN EN 837-1.



\*Leave blank for no optional items.

NOTES

(1) Meets NACE MR - 01 - 75/ISO 15156 recommendations.

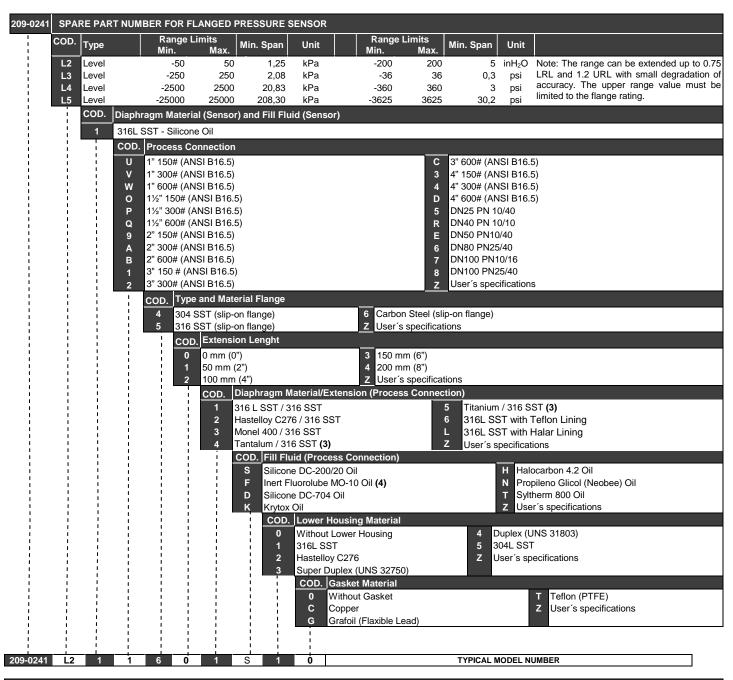
(2) Silicone Oil is not recommended for Oxygen (O2) or Chlorine service.

(3) Compliant with 3A-7403 standard for food and other applications where sanitary connections are required:

- Neobee M2O Fill Fluid

- Finishing wet Face: 0,8 µm Ra (32 µ" AA)

- Wet O-Ring: Viton, Buna-N and Teflon (4) Inert Fluid: Oxygen Compatibility, safe for oxygen service.



#### NOTES

(1) Silicone Oils not recommendations for Oxygen (O2) or Chlorine service.

(2) Not applicable for vacuum service.

(3) Attention, check corrosion rate for the process, tantalum plate 0.1 mm, AISI 316L extension 3 to 6mm.

(4) Fluorolube fill fluid is not available for Monel diaphragm.

(5) Inert Fluid: Safe for oxygen service.

# **TECHNICAL CHARACTERISTICS**

		Fu	nctio	nal Speci	ficatio	ns					
Process Fluid	Liquid, gas or s				noutio						
Output Signal and			trolled	according t	O NAML	JR NE	E43 Specifi	cation and with sup	erimposed digital		
Protocol Communication	communication	(HART	Proto	col). See the	figure b	elow.					
Power Supply	12 to 45 Vdc.										
				OPERATING							
		165	) <b> </b>						1		
	1500 -										
		E 100	)  -								
		<u>ō</u>									
Load Limitation		[000] [00m]	-								
		500	5  -				DIGIT	4-20mA AND TAL COMMUNICATION			
		25	0				4-20mA o	uply.			
		(		1			4-2011A 0	nny			
			12	20			30	40 4	-5		
					PO	NER S	UPPLY [Volt]				
Indiantar	Optional 4 <sup>1</sup> / <sub>2</sub> -digit numerical and 5-character alphanumerical LCD indicator.										
Indicator Hazardous Area								EPSI), non-incendiv	(EM_CSA and		
Certifications								tion proof (FM).			
Gertifications						,					
	Authorized representative in European Community Smar Gmbh-Rheingaustrasse 9-55545 Bad Kreuzanach										
		0									
	<b>PED Directive (97/23/EC) – Pressure Equipment Directive</b> This product is in compliance with the directive and it was designed and manufactured in accordance with										
	sound engineering practice using several standards from ANSI, ASTM, DIN and JIS.										
	<b>EMC Directive (2004/108/EC) - Eletromagnetic Compatibility</b> The EMC test was performed according to IEC standard: IEC61326-1:2006, IEC61326-2-3:2006,										
	IEC61000-6-4:2006, IEC61000-6-2:2005. For use in environment only.										
	Keep the shield insulated at the instrument side, connecting the other one to the ground if necessary to										
European Directive	use shielded cable.										
Information	ATEX Directive (94/9/EC) – Equipment and protective systems intended for use in potentially										
	explosive atmospheres.										
	This product was certified according European Standards at NEMKO and EXAM (old DMT). The certified										
	body for manufacturing quality assessment is EXAM (number 0158).										
	LVD Directive 2006/95/EC – Electrical Equipment designed for use within certain voltage limits										
	According the L	VD dire	ective /	Annex II the	equipme	ent un	der ATEX	"Electrical equipmer	nt for use in an		
	explosive atmo										
	The FC declara	itions of	confo	rmity for all a	applicab	le Fui	opean dire	ectives for this produ	ict can be found		
	at www.smar.		come	intro and	appricas		opourrand				
				T	emperat	ture L	imits				
	Ambient	-40	to	85 °C	-40	to	185 ⁰F				
	Ambient	-15	to	85 °C	-59	to	185 ⁰F	LD290I			
		-40	to	100 °C	-40	to	212 ºF	Silicone Oil			
Temperature Limits		0	to	85 °C	32	to	185 ºF	Fluorolube Oil			
	Process	-25	to	85 °C	-13	to	185 °F	Viton 'Ring			
		-40	to	150 °C		to	302 °F	LD290L			
		-15	to	150 °C	-59	to	302 °F	LD2901			
	Storage	40	to	100 °C	-40	to	212 °F	0			
	Digital	-20	to	80 °C	-4	to	176 °F	Operation			
	Display	-40	to	85 °C	-40	to	185 ºF	without damage			
Turn-on Time	Performs within	specifica	ations	in less than 5	second	s aftei	power is a	pplied to the transmi	tter.		

Zero and Span Adjustments	By configurator or local adjustment from 0 to 0.975 URL, URL = Upper Range Limit.							
Failure Alarm	In case of sensor or circuit failure, the self-diagnostics drives the output to 3.6 or 21.0 mA, according to the user's choice.							
Volumetric Displacement	Less than 0.15 cm <sup>3</sup> (0.01 in <sup>3</sup> )							
	14 MPa (2000 psi) for range 2,3 and 4. 31 MPa (4500 psi) for ranges 5.							
Overpressure Limits (MWP – Maximum Working Pressure)	For ANSI/DIN Level flanges ( <b>LD290L</b> models): 150 #: 6 psia to 235 psi (-0.6 to 16 bar) at 199.4 °F (93 °C) 300 #: 6 psia to 620 psi (-0.6 to 43 bar) at 199.4 °F (93 °C) 600 #: 6 psia to 1240 psi (-0.6 to 85 bar) at 199.4 °F (93 °C) PN10/16: -60 kPa to 1.02 MPa at 212 °F (100 °C) PN25/40: -60 kPa to 2.55 MPa at 212 °F (100 °C) These overpressures will not damage the transmitter, but a new calibration may be necessary.							
Damping Adjustment	0 to 128 seconds in addition to intrinsic sensor response time (0.2 s) (via digital communication).							
Humidity Limits	0 to 100% RH.							
Configuration	<ul> <li>Can be done through digital communication using the Hart Protocol or, partially, through local adjustment.</li> <li>Configurator         <ul> <li>CONF 401</li> <li>It works in the windows platform (95, 98, 2000, XP and NT).</li> <li>For equipment updates and HPC301 software, just check: www.smarreasearch.com</li> <li>Palm</li> <li>See Palm Handbook.</li> </ul> </li> </ul>							

	Performance Specifications								
Reference Conditions	Range starting at zero, temperature 25 °C (77 °F), atmospheric pressure, power supply of 24 Vdc, silicone oil fill fluid, isolating diaphragms in 316L SS and digital trim equal to lower and upper range values.								
Accuracy	For ranges 2, 3, 4 and 5: $\pm 0.075\%$ of span (for span >= 0.1 URL) $\pm [0.0375 + 0.00375$ URL/SPAN] % of span (for span < 0.1 URL) For Level Transmitter: $\pm 0.08$ % of span (for span ≥ 0.1 URL) $\pm [0.0504 + 0.0047$ URL/span] % of span (for span < 0.1 URL)								
	For Insertion Transmitter: ±0.2% of span								
Stability	± 0.15% of URL for 5 years								
	± [0.02 URL + 0.06% of span], per 20 °C (68 °F) for span >= 0.2 URL ± [0.023 URL+0.045% of span], per 20°C (68 °F) for span < 0.2 URL								
Temperature Effect	For Level Transmitter: $6 \text{ mmH}_2\text{O per } 20^{\circ}\text{C}$ for 4" and DN100. $17 \text{ mmH}_2\text{O per } 20^{\circ}\text{C}$ for 3" and DN80.								
Power Supply Effect	± 0.005% of calibrated span per volt.								
Mounting Position Effect	Zero shift of up to 250 Pa (1 inH <sub>2</sub> O), which can be calibrated out. No span effect.								
Electromagnetic	Designed to comply with, Approved according to IEC61326-1:2006, IEC61326-2-3:2006, IEC61000-6-								
Interference Effect	4:2006, IEC61000-6-2:2005.								

	Physical Specifications
Electrical Connection	See options in ordering code.
Process Connection	See options in ordering code.
Wetted Parts	316L SST and Hastelloy C276.
	Diaphragm for sanitary models available in Monel 400 and Tantalum.
Nonwetted Parts	Electronic Housing Injected aluminum with polyester painting or 316 SST. According to NEMA Type 4X or Type 4, IP66, IP66W*. *The IP66W sealing test (immersion) was performed at 1 bar for 24 hours. For any other situation, please consult Smar. IP66W tested for 200h to according NBR 8094 / ASTM B 117 standard.

	Level Flange (LD290L) 316L SST, 304 SST and Plated Carbon Steel. Fill Fluid Silicone or Fluorolube Oil.
Nonwetted Parts	Cover O-Rings Buna N.
	<b>Mounting Bracket</b> Optional universal mounting bracket for surface or vertical/horizontal 2"-pipe (DN 50) carbon steel with polyester painting or 316 SST. Accessories (bolts, nuts, washers and U-clamp) in carbon steel or 316 SST.
	Identification Plate 316 SST.
	Approximate Weights < 2.0kg (4 lb):aluminum.housing bracket.

## **Ordering Code**

CODE	Туре	Ra	nge Limits			Range Limits			
		Min.	Max.	Unit	Min.	Max.	Unit		
2	Gage	12.5	500	mbar	5.02	201.09	inH₂O		
3	Gage	62.5	2500	mbar	25.13	1005.45	inH₂O		
4	Gage	0.625	25	bar	157.1	10054.5	inH <sub>2</sub> O		
5	Gage	6.25	250	bar	90.65	3625.94	psi		
i	CODE	Diaphragn	n Material a	nd Fill Fluid					
-	1	316L SST -	Silicone Oil						
i	2	316L SST –	Inert Fluorol	ube Oil <b>(2)</b>					
ł	3	Hastelloy C2	276 - Silicone	e Oil <b>(1)</b>					
	4	Hastelloy C2	276 – Inert F	luorolube Oil	(2)				
	D	316L SST -	Inert Krytox	Oil <b>(2)</b>					
- i	E	Hastelloy Ca	276 – Inert K	rytox Oil (2)					
Ì	Q			rbon 4.2 Oil <b>(</b>	-				
1	R			alocarbon 4.2	.,				
	i			ections Mate	erial				
i			stelloy C276	(1)					
1			6L SST	<i>e</i>					
1			er's specifica						
-	į	C		al Indicator					
i				out Indicator	•	1	With Indicat	or	
-		!	CODI		Connections				
			1		PT - Female		U	1/2 BSP – Male	learsted to the transmitter
-	i	i	A	M20 X 1,5	IN 16288 - Form	D	v x	1" NPT Sealed	tegrated to the transmitter
i	1		G Н		16288 - Form D		z	User's specification	วกร
i			м		PT - Male		2	Oser s specification	5115
-					Electrical Conn	actions			
ļ	i	i			1/2 - 14 NPT (3)	ections		A	M20 X 1.5 (5)
i		1			1/2 - 14 NPT X 3	/4 NPT (316 S	ST) - with ada	B	PG 13.5 DIN (5)
					1/2 - 14 NPT X 3	-		~ ~ ~ ~	User's specifications
					1/2 - 14 NPT X 1	-			
	i	i	i i		1/2 - 1/2 NPTF (3				
i i	:				1/2 - 3/4 NPTF (	-	-		
Ì	ł			:	CODE Mounti	ng Bracket			
			: :			o Mounting Brack	ket		
-	i			1		-		Carbon Steel acce	ssories
	i	i I	1					SST accessories	
i					7 Carbon S	Steel Mounting	Bracket with	316 SST accessor	ies
-	1				A Flat; 304	SST Mounting	Bracket with	316SST accessor	ies
					CODE	Optional Items	s		
				i					

\* Leave blank for no optional items.

MODEL	GAGE P	RESSUR	RE TRAN	ISMITTER	(CONTIN	IUATION)							
	CODE	Output	Signal										
	G0	4-20 m/	4										
	1	CODE	Housir	ng Materia	l (9) (10)								
	:	H0	Alumini	um (IP/TYF	PE)				H3	316 S	ST for Saline Atmosp	phere (	IPW/TYPEX) <b>(8)</b>
!		H1	316 SS	T (IP/TYPE	E)				H4	Coppe	er Free Aluminium fo	r Saline	e Atmosphere (IPW/TYPEX) (8)
		H2	Alumini	um for Sal	line Atmo	sphere (IPW/TY	(PEX) (8)						
			CODE	Identifi	cation Pl	ate				_			
	i		11	FM: XP,	IS, NI, DI		14	EXA	M (DMT):	: Ex-ia;	NEMKO: Ex-d	17	EXAM (DMT) Grupo I, M1 Ex-ia
i	i		12	NEMKO:	Ex-d, Ex-	ia	15	CEPE	EL: Ex-d,	, Ex-ia		ID	NEPSI: Ex-ia, Ex-d
	i i	:	13	CSA: XP	, IS, NI, D	l l	16	Witho	out Certif	ication	I	IJ	NEMKO: Ex-d
	I I	-		CODE	Paintin	g							
			ł	P0	Munsell	N 6,5 Gray				P5	Polyester Yellow		
			i	P3	Polyeste	er Black				P8	Without Painting		
		i	į	P4	Epoxy V	Vhite				P9	Blue Safety Base E	роху –	Eletrostatic Painting
i	i				CODE	Display Unit	1						
				i i	Y0	Percentage					Y3 Temperature	(Tempe	erature)
		-			Y1	Current (mA)					YU User's specific	cation (	(7)
-	-				Y2	Pressure (Eng	g. Unit)						
		i	į		· · ·	CODE Disp	lay Unit 2	2					
i	i	i	i	1	1		entage				Y6 Temper	ature (	Temperature)
i	i	!			I I		ent (mA)				YU User's s		,
		1	1				sure (Eng	. Unit)					
1				i		COL	DE Tag F	Plate					
		ł	ļ		i i	JC					J2 Use	r's spe	cification
	1	ł		1	i	J1		ut TAC	2				
		i	i	1			with		2				
	<u> </u>	i											
LD291M	Ġ0	H0	11	P0	Y0	Y5 J0	→ (	TYPI	CAL MOI	DEL N	UMBER		

## **Optional Items**

Special Procedures	C1 – Degrease Cleaning (Oxygen or Chlorine Service)
Burnout	BD – Down Scale BU – Up Scale
Características Especiais	ZZ – User Specification

#### NOTES

(1) Meets NACE material recommendation per MR-01-75.

(2) Inert fluid: safe for oxygen service.

(3) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM, FM, CSA).

(4) Certificate for use in Hazardous Locations (CEPEL, CSA).
(5) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM).

(6) Not certified for use in hazardous locations.

(7) Limited values to 4 1/2 digits; limited unit to 5 characters.

(8) IPW/TYPEX was tested for 200 hours according to NBR 8094 / ASTM B 117 standard.

(9) IPX8 tested for 10 meters of water column for 24 hours.

(10) Ingress Protection:

Products	CEPEL	NEMKO/EXAM	FM	CSA	NEPSI
LD29X	IP66/W	IP66/68/W	Type 4X/6/6P	Type 4X	IP67

MODEL	SANITA	RY PRESS	URE TRA	ANSMITT	TERS						
LD291S											
	CODE	Туре	F	Range Li	imits			F	Range Limit	s	
			Min.	N	lax.	Unit		Min.	Max.	Unit	
	2	Sanitary	12.5	Į	500	mbar		5.02	201.0	) inH₂O	)
	3	Sanitary	62.5	2	500	mbar		25.13	1005,4	5 inH <sub>2</sub> O	)
	4	Sanitary	0.625		25	bar		157.1	10054	5 inH <sub>2</sub> C	)
	5	Sanitary	6.25	55	.15	bar		90.65	799.8	9 psi	i
		CODE	Diaphra	gm Mate	erial						
i	i	I	316L SS	т							
Ì		:	CODE	Fill Fluid	t						
	ł		s s	Silicone D	C-200/2	0 Oil					
	ł			CODE	Local	Indicator					
	i	i		0	Withou	ut Indicato	r				
1	-	1		1	With Ir	ndicator					
1	ļ		!	-	CODE	Proces	ss Conn	ections			
	ł	ł	-	ł	В	Thread	I IDF - 2"	300# <b>(2)</b>	н	DN40 30	00# - DIN 11851
	į	i	i	i	С	Thread	RJT - 2	" 300#	Р	Tri-Clam	p - 2" 800# <b>(2)</b>
	-		-		D		mp - 2" 3		Q	Tri-Clam	p - 1 1/2" 800# <b>(2)</b>
	ļ			ļ	E			2" 300# <b>(2)</b>	Z	User's sp	pecifications
	-	-	-	-	F			/2" 300# <b>(2</b> )			
	i	i	i	i	i			cal Conne	ctions		
	:	1	1	:	1	0		4 NPT <b>(3)</b>			A M20 X 1.5 (5) B PG 13.5 DIN (5)
!	-		-			1			,	SST) - with a	Z User's specifications
-	ł	ł	1	ł		2			-	SST) - with a	
	i	i	i	i	i	3			-	SST) - with a	adapter (9)
1		:	:	-	1	4			16 SST) - w 16 SST) - w	-	
-	-	1	-			5				illi adapter	
-							CODE				V Viton (2)
	i	i	i	i	i	i	0 B	Without Buna-N	-		Z User's specifications
				1			Т	Teflon (2			
							1		-) Adaptation	Sloovo	
						!			Without Sle		
i	i	i		i	i	i	i	-		ation Sleeve	in 316 SST
	-	-			i i	Ì		-	-	Clamp Coni	
				-						hout Clamp	
		-		1						h Tri-Clamp	
	i	i	i		i	i	i				ragm Material (Sanitary Connection)
				1			1				elloy C276
		ł						i			_SST
						!					E Fill Fluid (Sanitary Connection)
	i				i	i				D	Silicone DC-704 Oil
-	i i		1			i			-	F	Fluorolube MO-10 Oil (1)
	ł									N	Propilene Glicol (Neobee) Oil (2)
	-			1	!	!				S	Silicone DC-200/20 Oil
						;			i I	т	Syltherm 800 Oil
	i					-				Z	User's specifications
	i			i I	i	i	i		1		CODE Optional Items
	1	1	-	1		:				; ;	
	1			-	!	!	!	i I			
LD291S	2	1	N	1	D	0	v	1	2	i D	* ← Typical Model Number
	-						<u> </u>				

\*Leave blank for no optional items.

	COD.	Output				ONTINUA								
	G0	4-20 m/												
	1													
		COD.		lousing Material (7) (8) uminium (IP/TYPE)										
	1	HO		,	,									
	ł	H1		T (IP/TYPE	,	. 4 .								
	i	i	COD.		cation Pl	ate			EV					
	i	i	I1	FM: XP, I		•		14 		•	,	Ex-ia; NEMKO: Ex-d		
	1		12	NEMKO: CSA: XP,				15		PEL: E				
		ł	13					16	I6 Without Certification					
		:		COD.	Paintin				_		<b>.</b>			
	ł	ł	i		P0 Munsell N 6,5 Gray					P5		vester Yellow		
	i	i		-	P3 Polyester Black					P6	Ерох	xy Yellow		
	i	Ì		P4	Epoxy V	0								
				i	COD.	Display								
				1	Y0	Percenta	0				Y3	Temperature (Temperature)		
				1	Y1	Current (					YU	User's specification (6)		
			i i	1	Y2	Pressure		,						
	i	i		1			-	y Unit 2	2					
	i	i					Percer	•				Y6 Temperature (Temperature)		
				i.			Curren	. ,				YU User's specification (6)		
			1	i		Y5		re (Eng		,				
				1	i	-	COD.	_						
			i i	1	i		JO	With	TAG			J2 User's specification		
			i	1			J1	Witho	out T	AG				
		i	i	1			i							
91S	GO	H0	11	P0	YO	Y5	JO	٦	<b>T</b> 1/1			DEL NUMBER		

## **Optional Items**

Special Procedures	C1 –Degrease Cleaning (Oxygen or Chlorine Service) C4 - Polishing of the sanitary connections according to 3A Certification (2)
Burnout	BD – Down Scale BU – Up Scale

#### NOTE

(1) Inert Fluid: safe for oxygen service.(2) Compliant with 3A-7403 standard for food and other applications where sanitary connections are required.

- Neobee M2O Fill Fluid

Finishing wet Face: 0.8 μm Ra (32 μ" AA)
Wet O-Ring: Viton, Teflon and Buna-N

(3)Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM, FM, CSA).

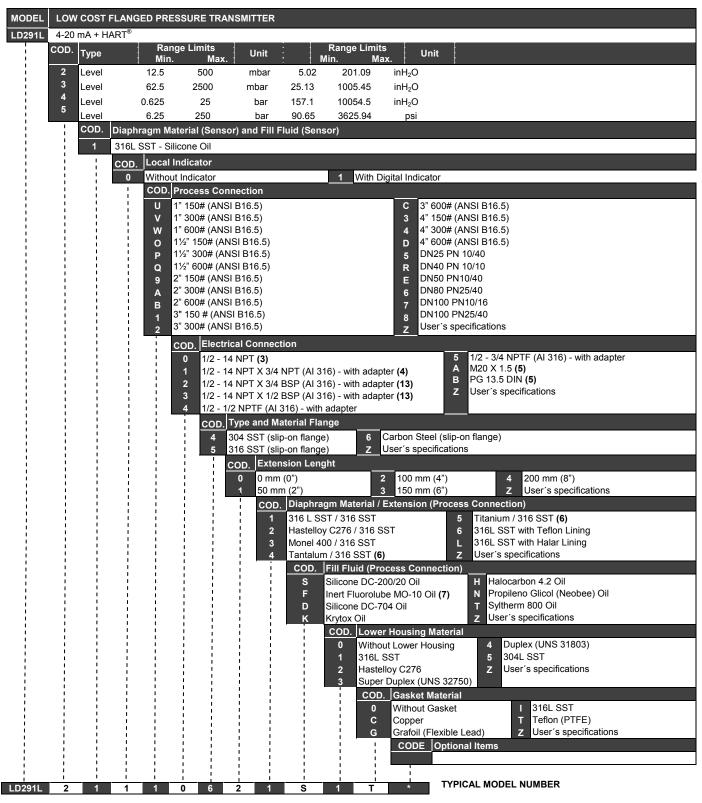
(4) Certificate for use in Hazardous Locations (CEPEL, CSA).
(5) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM).

(6) Limited values to 4 1/2 digits; limited unit to 5 characters.

(7) IPX8 tested for 10 meters of water column for 24 hours.(8) Ingress Protection:

Produtos	CEPEL	NEMKO/EXAM	FM	CSA	NEPSI
LD29X	IP66/W	IP66/68/W	Type 4X/6/6P	Type 4X	IP67

(9) Not certified for use in hazardous locations.



\*Leave it blank when there are not optional items.

MODEL				PRESSUR	E TRANS	MITTER	(CONTIN	IUATIC	DN)					
	COD.	Output	Signal											
	G0	4-20 m/	Ą											
	:	COD.	Housin	ng Materia	l (11) (12)	)								
	i	H0	Alumini	um (IP/TYF	PE)					H3	316 SST for	r saline atmos	sphere (	(IPW/TYPEX) <b>(10)</b>
1	1	H1	316 SS	T (IP/TYPE	)					H4	Copper Fre	e Aluminium	for Salir	ne Atmosphere (IPW/TYPEX) (10)
	!	H2	Alumini	um for salir	ne atmos	ohere (IP	W/TYPE	K) <b>(10)</b>						
	ł		COD.	Identifie	cation Pla	ate			-					_
	i	i	<b>I</b> 1	FM: XP, I	S, NI, DI			14	EXAM	(DMT):	Ex-ia; NEM	KO: Ex-d	17	EXAM (DMT) Grupo I, M1 Ex-ia
i i			12	NEMKO:	Ex-d, Ex-	ia		15	CEPEL	: Ex-d,	Ex-ia		IJ	NEMKO: Ex-d
1		!	13	CSA: XP	IS, NI, D	1		16	Withou	t Certifi	cation			
	!	ł		COD.	Painting	9								
	ł	i	ł	P0	Munsell	N 6,5 Gr	ay			P6	Epoxy Yello	ow		
	i		i	P3	Polyeste					P8	Without Pa	iinting		
i i			-	P4	Ероху V	Vhite				P9	Blue Safety	y Base Epoxy	– Eletro	ostatic Painting
1			1	P5	Polyeste	er Yellow				PC	Safety Bas	e Polyester –	Eletros	tatic Painting
					COD.	Display	v Unit 1							
	i		ł	i i	Y0	Percent	age				Y3	Temperature	e (Temp	perature)
	i	Ì	i	1	Y1	Current					YU	User's speci	ification	(9)
		ł	1		Y2	Pressur	re (Eng. L	Jnit)						
1		ł	1		ł	COD.	Display	v Unit 2	1					
1			-		į	Y0	Percent	age				Y6 Tempe	erature	(Temperature)
-	ł	i	i			Y4	Current	• •				YU User's	specifie	cation (9)
i	i				1	Y5	Pressur	e (Eng	. Unit)					
i I		ł	1	-	!	ł	COD.							
1	1					i	JO	With 7	ſAG			J2 Us	er's spe	ecification
!			ł	i	į	ł	J1	Witho	ut TAG					
	i	i	i	:	:	-								
LD291L	Ġ0	H0	I1	P0	Y0	Y5	JO	←	TYPICA	L MOE	DEL NUMBE	R		

## **Optional Items**

Special Procedures	C1 – Degrease Cleaning (Oxygen or Chlorine Service)
Burnout	BD – Down Scale
Lower Housing Connection	BU – Up Scale         U0 – With 1 Flush Connection 1/4" NPT (if supplied with lower housing)         U1 – With 2 Flush Connections 1/4" NPT per 180°         U2 – With 2 Flush Connections 1/4" NPT per 90°         U3 – With 2 Flush Connections 1/2" - 14 NPT per 180° (with cover)         U4 – Without Flush Connection

#### NOTES

(1) Silicone Oils not recommendations for Oxygen (O<sub>2</sub>) or Chlorine service.

(2) Not applicable for vacuum service.

(3) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM, FM, CSA).

(4) Certificate for use in Hazardous Locations (CEPEL, CSA).

(5) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM).

(6) Attention, check corrosion rate for the process, tantalum plate 0.1 mm, AISI 316L extension 3 to 6mm.

(7) Fluorolube fill fluid is not available for Monel diaphragm.

(8) Inert Fluid: Safe for oxygen service.

(9) Limited values to 4 1/2 digits; limited unit to 5 characters.

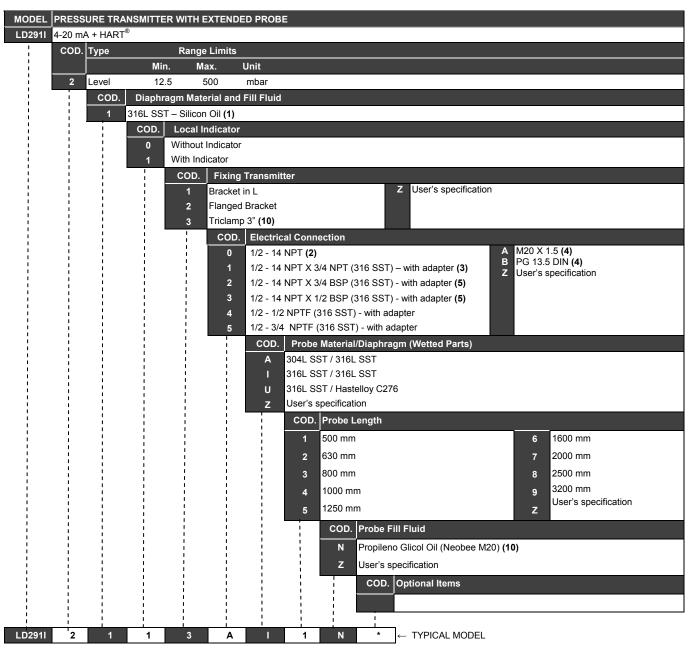
(10) IPW/TYPEX was tested for 200 hours according to NBR 8094 / ASTM B 117 standard.

(11) IPX8 tested for 10 meters of water column for 24 hours.

(12) Ingress Protection:

Products	CEPEL	NEMKO/EXAM	FM	CSA	NEPSI
LD29X	IP66/W	IP66/68/W	Type 4X/6/6P	Type 4X	IP67

(13) Not certified for use in hazardous locations.



\*Leave blank for no optional items.

MODEL	PRESS	URE TR	ANSMIT	TER WITH	EXTEND	ED PRO	BE (CONTINUATION)				
	COD.	Output	Signal								
-	G0	4-20 mA	Ą				G2 10-50 mA				
i i	G1	0-20 mA									
i		COD.	Housin	g Materia	(8) (9)						
		H0	Aluminiu	ım (IP/TYF	PE)			H3	316 SST for saline atmosphere (IPW/TYPEX) (7)		
		H1	316 SST	(IP/TYPE	)			H4	Copper Free Aluminium for Saline Atmosphere (IPW/TYPEX) (7)		
		H2	Aluminiu	um for salir	ne atmosp	here (IPV	N/TYPEX) (7)				
			COD.	Identific	ation Pla	ate					
i		i	IN	CEPEL: E	Ex-ia						
	i i	ł	i	COD.	Painting	J					
1	1	!	!	P0	Munsell	N 6,5 Gra	ау	P6	Epoxy Yellow		
		ł		P3	Polyeste	r Black		P8	Without Painting		
ļ		i	i	P4	Ероху И	/hite		Р9	Blue Safety Base Epoxy – Eletrostatic Painting		
i				P5	Polyeste	Polyester Yellow			Safety Base Polyester – Eletrostatic Painting		
				i	COD.	Display	Unit 1				
			!	i	Y0	Percenta	age		Y3 Temperature (Temperature)		
			i i	i	Y1	Current	(mA)		YU User Specification (6)		
i		i	i	1	Y2	Pressure	e (Eng. Unit)				
			:	1		COD.	Display Unit 2				
	:		1		i	Y0	Percentage		Y6 Temperature (Temperature)		
				i	1	Y4	Current (mA)		YU User Specification (6)		
			i		1	Y5	Pressure (Eng. Unit)				
i		i i	i	1	1		COD. Tag Plate				
	i	ł	:	1	ļ	i	J0 With TAG		J2 User Specification		
	1		1		Ì	1	J1 Without TAG				
			ł	i i		-	1				
LD2911	G0	H0	IN	P0	YO	Y5	, 	TYPI	CAL MODEL NUMBER		

## **Optional Items**

Special Procedures	C1 – Degrease Cleaning (Oxygen or Chlorine Service)
	C4 - Polishing of the sanitary connections according to 3A Certification (10)
Burnout	BD – Down Scale
	BU – Up Scale
Special Characteristics	ZZ – User's specifications

#### NOTES

(1) Silicone Oils not recommendations for Oxygen (O<sub>2</sub>) or Chlorine service.

- (2) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM, FM, CSA).
- (3) Certificate for use in Hazardous Locations (CEPEL, CSA).
- (4) Certificate for use in Hazardous Locations (CEPEL, NEPSI, NEMKO, EXAM).

(5) Not certified for use in hazardous locations.

(6) Limited values to 4 1/2 digits; limited unit to 5 characters.

(7) IPW/TYPEX was tested for 200 hours according to NBR 8094 / ASTM B 117 standard.

(8) IPX8 tested for 10 meters of water column for 24 hours.

(9) Ingress Protection:

Products	CEPEL	NEMKO/EXAM	FM	CSA	NEPSI
LD29X	IP66/W	IP66/68/W	Type 4X/6/6P	Type 4X	IP67

(10) Compliant with 3A-7403 standard for food and other applications where sanitary connections are required.

- Neobee M2O Fill Fluid

- Finishing wet Face: 0.8  $\mu m$  Ra (32  $\mu "$  AA)

- Wet O-Ring: Viton, Teflon and Buna-N

# **CERTIFICATIONS INFORMATIONS**

## **European Directive Information**

Authorized representative in European Community

Smar Gmbh-Rheingaustrasse 9-55545 Bad Kreuzanach

#### PED Directive (97/23/EC) – Pressure Equipment Directive

This product is in compliance with the directive and it was designed and manufactured in accordance with sound engineering practice using several standards from ANSI, ASTM, DIN and JIS.

#### EMC Directive (2004/108/EC) - Eletromagnetic Compatibility

The EMC test was performed according to IEC standard: IEC61326-1:2006, IEC61326-2-3:2006, IEC61000-6-4:2006, IEC61000-6-2:2005. For use in environment only.

Keep the shield insulated at the instrument side, connecting the other one to the ground if necessary to use shielded cable.

# ATEX Directive (94/9/EC) – Equipment and protective systems intended for use in potentially explosive atmospheres.

This product was certified according European Standards at NEMKO and EXAM (old DMT). The certified body for manufacturing quality assessment is EXAM (number 0158).

# LVD Directive 2006/95/EC – Electrical Equipment designed for use within certain voltage limits

According the LVD directive Annex II the equipment under ATEX "Electrical equipment for use in an explosive atmosphere" directive are excluded from scope from this directive.

The EC declarations of conformity for all applicable European directives for this product can be found at <u>www.smar.com</u>.

## **Other Aprovals**

#### **FMEDA Report**

#### **Certifier Body: Exida**

Failure Modes, Effects and Diagnostics Analysis (Report No. R02 / 11-19).

### Hazardous Locations Certifications

The IP68 sealing test (immersion) was performed at 1 bar for 24 hours. For any other situation, please consult Smar.

### **North American Certifications**

#### **FM Approvals**

#### Certificate N: FM 4B9A4.AX

Explosion-proof for Class I, Division 1, Groups A, B, C, and D; Dust-ignition proof for Class II, Division 1, Groups E, F, and G; Class III, Division 1; hazardous locations. Intrinsically Safe for use in Class I, Division 1, Groups A, B, C, and D; Class II, Division 1, Groups E, F, and G; Class III, Division 1; Non-incendive for Class I, Division 2, Groups A, B, C, and D Entity parameters:  $V_{max} = 30$  Vdc I<sub>max</sub> = 110 mA Ci = 8nF Li = 0.24 mH Ambient Temperature: (-40°C < T<sub>amb</sub> <+60°C). Enclosure Type: 4X or Type 4.

#### CSA International (Canadian Standards Association)

#### Certificate N: CSA1111005

Class 2258 02 Hazardous Locations for Class I, Division 1, Groups B, C and D; Class II, Division 1, Groups E, F and G; Class III, Division 1; Class I, Division 2, Groups A, B, C and D; Class II, Division 2, Groups E, F and G; Class III.

Class 2258 03 Intrinsically Safe and Non-Incendive Systems for Class I, Division 1, Groups A, B, C e D, Class II, Division 1, Groups E, F e G, Class III, Division 1. Intrinsically Safe when connected through CSA Certified Diode Safety Barrier, 28 V<sub>max</sub>, 300  $\Omega_{min}$ .

Class 2258 04 Intrinsically Safe, Entity for Class I, Division 1, Groups A, B, C and D; Class II, Division 1, Groups E, F and G; Class III, Division 1. Intrinsically safe with entity parameters: Vmax = 28 V, Imax = 100 mA, Ci = 5 nF, Li = 0 uH, when connected through CSA Certified Safety Barriers. Ambient Temperature: ( $-20^{\circ}C < T_{amb} < +40^{\circ}C$ ). Enclosure Type: 4 or Type 4X.

#### **European Certifications**

#### Certificate No: Nemko 03 ATEX 133X

ATEX Intrinsically Safe Group II 1GD, Ex ia IIC T4 Entity Parameters: Pi = 0.7 W Ui = 28 V Ii = 100 mA Ci = 2 nF Li = Neg Ambient Temperature: (-20 °C < T<sub>amb</sub> <+62 °C).

#### Certificate No: Nemko 02 ATEX 149X

ATEX Explosion Proof Group II 2G, Exd IIC T6 Enclosure Type: IP66/68 or IP66/68W

Special conditions for safe use:

1. The transmitters are marked with three options for the indication of the protection code. The certification is valid only when the protection code is indicated in **one** of the boxes following the code.

The following options apply:

• Ex d IIC T6 () with X ticked in the parenthesis:

The Ex d IIC T6 protection according to certificate Nemko 02ATEX035X / 02ATEX149X applies for the specific transmitter. Certified Ex d IIC cables entries shall be used.

• Ex ia IIC T4 () with X ticked in the parenthesis:

The Ex ia IIC T4 protection according to certificate Nemko 03ATEX133X applies for the specific transmitter. Certified diode safety barriers shall be used.

- Ex d IIC T6 / Ex ia IIC T4 () with X ticked in the parenthesis:
- The transmitter has double protection. Both Ex d IIC T6 and Ex ia IIC T4 protection apply for the specific transmitter according to certificates Nemko 02ATEX035X/ 02ATEX149X and Nemko 03ATEX133X. In this case the transmitter shall be fitted with appropriate certified cable entries Ex d IIC and the electric circuit supplied by a certified diode safety barrier as specified for the protection Ex ia IIC T4.

2. For enclosures of the transmitters made of aluminum impact and friction hazards shall be considered when the transmitter is used in category II 1 G according to EN 50284 clause 4.3.1.

3. The diode safety barrier shall have a linear resistive output characteristic.

4. The pressure of the potentially explosive atmosphere surrounding the transmitter shall be within the range 0.8 mbar to 1.1 mbar.

#### Certificate No: DMT 01 ATEX E 059

ATEX Intrinsically Safe Group II 1/2 G, Ex ia, IIC T4/T5/T6 Ambient Temperature: -40  $^{\circ}$ C < T<sub>amb</sub> <+85  $^{\circ}$ C Entity Parameters: Ui = 28 Vdc Ii = 93 mA Ci ≤ 5 nF Li = neg

#### **South American Certifications**

#### Certificado No: CEPEL-Ex-049/95

Intrinsicamente Seguro - Ex-ia IIC T5 • Parâmetros: Ui = 30 Vdc li = 100 mA Ci =6,4nF Li = neg Pi=0,7 W Temperatura Ambiente: (-20 °C <  $T_{amb}$  <+50 °C).

#### Certificado No: CEPEL-Ex-039/96 Á Prova de Explosão - Ex-d IIC T6

Temperatura Ambiente: (-20 °C < T<sub>amb</sub><+40 °C). Grau de proteção: IP66 ou IP66W.

### **Asian Certifications**

### Certificate No: Nepsi GYJ05602

Intrinsically safe - Ex ia, IIC T4/T5/T6 Ambient Temperature: -40 °C < T<sub>amb</sub> <+85 °C Entity Parameters: Ui = 28 Vdc Ii = 93 mA Ci ≤ 5 nF Li = neg

### Certificate No: Nepsi GYJ05601

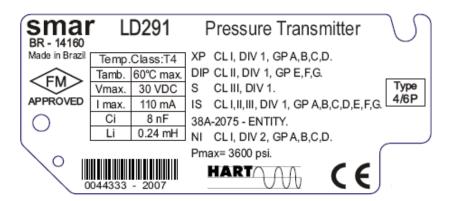
Explosion proof - Ex d IIC T6 Ambient Temperature: -20 °C < T<sub>amb</sub> <+40 °C.

## Identification Plate and Control Drawing

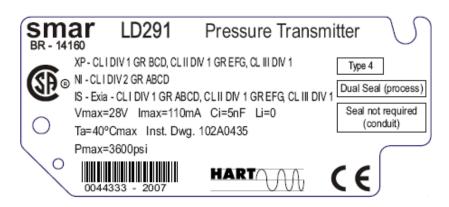
### **Identification Plate**

• Identification of Intrinsically Safe and Explosion Proof for gas and steam:

### FΜ



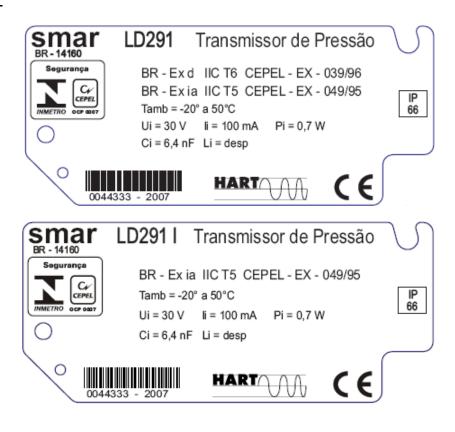
CSA



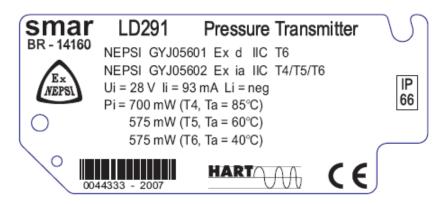
LD291 Pressure Transmitter smar BR - 14160 N II 2G Ex d IIC T6 () Nemko 02 ATEX149X IP66 II 1GD Ex ia IIC T4 T62°C () Nemko 03 ATEX133X II 2G Ex d IIC T6 / II 1GD Ex ia IIC T4 T62°C ( ) **IP68** 10m/24h Only one code marked with a " X " is valid. Ui = 28 V Ii = 100 mA Pi = 0.7 W Ci = 2 nF Li = 0 0 HART/ E 0470 0044333 - 2007 smar LD291 Pressure Transmitter BR - 14160 II 1/2G Ex ia IIC T4/T5/T6 DMT01ATEXE059 () Pi = 760 mW (T4,Ta = 75°C) -40°C ≤ Ta ≤ +85°C **IP66** 700 mW (T4,Ta = 85°C) Ui = 28 VDC Ii = 93 mA 575 mW (T5,Ta = 60°C) Li = neg  $Ci \le 5 nF$ **IP68** 575 mW (T6,Ta = 40°C) 10m/24h II 2G Ex d IIC T6 Nemko 02 ATEX 149X ( )  $\bigcirc$ C € 0470 HART 0044333 - 2007

CEPEL

**NEMKO and DMT** 

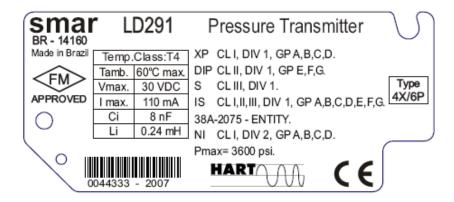


NEPSI

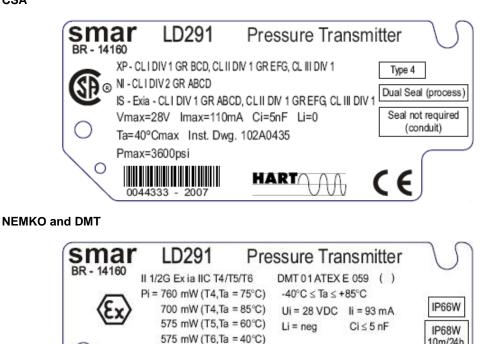


Identification if Intrinsically Safe and Explosion Proof for saline atmospheres:

FΜ



CSA



HAR'

Nemko 02 ATEX 149X ( )

E 0470

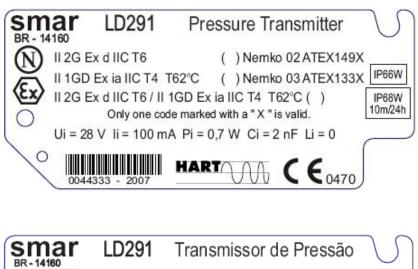
II 2G Ex d IIC T6

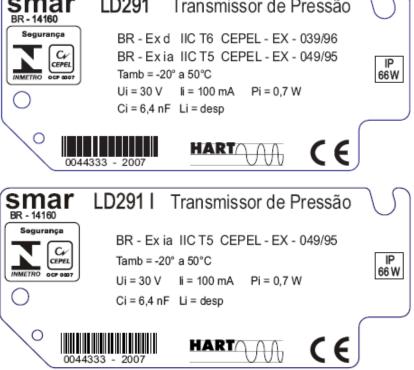
0044333

 $\cap$ 

10m/24h

CEPEL

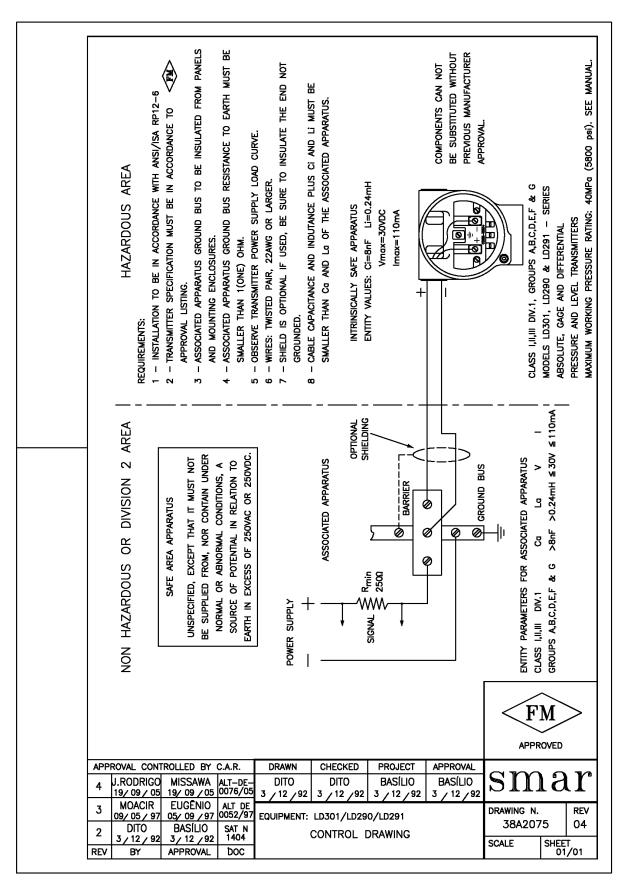




### **Control Drawing**

CSA





HAZARDOUS AREA Requirements: 1 - INSTALLATION TO BE IN ACCORDANCE WITH IEC 60079-14	<ol> <li>2 - TRANSMITTER SPECIFICATION MUST BE IN ACCORDANCE TO Nemko APPROVAL LISTING.</li> <li>3 - ASSOCIATED APPARATUS GROUND BUS TO BE INSULATED FROM PANELS AND MOUNTING ENCLOSURES.</li> <li>4 - ASSOCIATED APPARATUS GROUND BUS RESISTANCE TO EARTH MUST BE SMALLER THAN 1(ONE) OHM.</li> <li>5 - OBSERVE TRANSMITTER POWER SUPPLY LOAD CURVE.</li> <li>6 - WIRES: TWISTED PAIR, 224WG OR LARGER.</li> </ol>	- Shiel Grol - Cabl	INTRINSICALLY SAFE APPARATUS ENTITY VALUES: CI=ZnF Li=0 UI=28VDC II=100mA PI=0.7W	PERVICE ANUTATION OF A APPROVAL		MODELS LD301, LD290 & LD291 - SERIES ABSOLUTE, GAGE AND DIFFERENTIAL PRESSURE AND LEVEL TRANSMITTERS.
NON HAZARDOUS AREA	SAFE AREA APPARATUS UNSPECIFIED, EXCEPT THAT IT MUST NOT BE SUPPLIED FROM, NOR CONTAIN UNDER NORMAL OR ABNORMAL CONDITIONS, A SOURCE OF POTENTIAL IN RELATION TO EARTH IN EXCESS OF 250VAC OR 250VDC.	POWER SUPPLY	SIGNAL Rmin SIGNAL SHELDING	CROUND BUS	11Y PARAMETER /2 GD EE× ia = Ci + Cable	Lo = Li + Cable Capacitance Vo ≦ 28V I o ≦ 100mA Um= Check the maximum voltage allowed
APPROVAL	CONTROLLED BY C.A.R.	MOACIR CA 20/05/03 20 EQUIPMENT: LD:	HECKED PROJECT SSIOLATO RICARDO 1/05/03/20/05/03 290/LD291/LD301 NTROL DRAWING	APPROVAL CASSIOLATO 5 20 / 05 / 03	DRAWING N. 102A09 SCALE	REV

smai	6	SRF – Service Request Form Pressure Transmitters						Proposal No.:				
Company:	Unit:							Invoice:				
	COMMERCIA			TECHNICAL CONTACT								
Full Name:					Full Name:							
Function:					Function:							
Phone: Extension:					Phone: Extension:							
Fax:					Fax:							
Email: Email:												
EQUIPMENT DATA           Model:         Serial Number:         Sensor Number:												
Technology:						Version Firmware:						
()4-20 mA ()HART®	() FOU	NDATION fieldbus <sup>™</sup>	() PROF									
Process Fluid:												
Calibration Range Ambient Temp			ature ( ⁰F )	( °F ) Process Temperature ( °F )		perature ( ºF )	Process Pressure					
Min.: Ma	in.: Max.: M		Min.: Max.:			Max.:	Min.:	Max.:				
Static Pressur	Pressure Vacuum		n									
Min.: Ma	ax.:	Min.: M	lax.:									
Normal Operation Time: Failure Date:												
	(Ple	ase, describe the obs	FAILURE DI erved behavior			ow it reproduces,	etc.)					
			OBSER	VATIOI	NS							
			USER INF	ORMA	ΓΙΟΝ							
Company:												
Contact:		Title			Section:							
Phone:		Extension:	sion: E-m			ail:						
Date:				Signa	ture:							
For warranty or non-warran Further information about a	ty repair, pleas ddress and co	se contact your representacts can be found or	entative. n <u>www.smar.c</u>	om/co	ntactus.asp							

# **SMAR WARRANTY CERTIFICATE**

- 1. SMAR guarantees its products for a period of 24 (twenty four) months, starting on the day of issuance of the invoice. The guarantee is valid regardless of the day that the product was installed.
- 2. SMAR products are guaranteed against any defect originating from manufacturing, mounting, whether of a material or manpower nature, provided that the technical analysis reveals the existence of a quality failure liable to be classified under the meaning of the word, duly verified by the technical team within the warranty terms.
- 3 Exceptions are proven cases of inappropriate use, wrong handling or lack of basic maintenance compliant to the equipment manual provisions. SMAR does not guarantee any defect or damage caused by an uncontrolled situation, including but not limited to negligence, user imprudence or negligence, natural forces, wars or civil unrest, accidents, inadequate transportation or packaging due to the user's responsibility, defects caused by fire, theft or stray shipment, improper electric voltage or power source connection, electric surges, violations, modifications not described on the instructions manual, and/or if the serial number was altered or removed, substitution of parts, adjustments or repairs carried out by non-authorized personnel; inappropriate product use and/or application that cause corrosion, risks or deformation on the product, damages on parts or components, inadequate cleaning with incompatible chemical products, solvent and abrasive products incompatible with construction materials, chemical or electrolytic influences, parts and components susceptible to decay from regular use, use of equipment beyond operational limits (temperature, humidity, etc.) according to the instructions manual. In addition, this Warranty Certificate excludes expenses with transportation, freight, insurance, all of which are the customer's responsibility.
- 4. For warranty or non-warranty repair, please contact your representative.

Further information about address and contacts can be found on www.smar.com/contactus.asp

- 5. In cases needing technical assistance at the customer's facilities during the warranty period, the hours effectively worked will not be billed, although SMAR shall be reimbursed from the service technician's transportation, meals and lodging expenses, as well dismounting/mounting costs, if any.
- 6. The repair and/or substitution of defective parts do not extend, under any circumstance, the original warranty term, unless this extension is granted and communicated in writing by SMAR.
- 7. No Collaborator, Representative or any third party has the right, on SMAR's behalf, to grant warranty or assume some responsibility for SMAR products. If any warranty would be granted or assumed without SMAR's written consent, it will be declared void beforehand.
- 8. Cases of Extended Warranty acquisition must be negotiated with and documented by SMAR.
- 9. If necessary to return the equipment or product for repair or analysis, contact us. See item 4.
- 10. In cases of repair or analysis, the customer must fill out the Revision Requisition Form (FSR) included in the instructions manual, which contains details on the failure observed on the field, the circumstances it occurred, in addition to information on the installation site and process conditions. Equipments and products excluded from the warranty clauses must be approved by the client prior to the service execution.
- 11. In cases of repairs, the client shall be responsible for the proper product packaging and SMAR will not cover any damage occurred in shipment.

- 12. Responsibility: Except for the above-mentioned general warranty conditions for SMAR products, SMAR will not assume any responsibility before the customer, without limitation, for damages, consequences, indemnity claims, loss of earnings, service expenses and other costs caused by the non-observation of the installation, operation and maintenance instructions included in SMAR manuals. Furthermore, the buyer also agrees to exempt the supplier for indemnity of damages (with exception to costs for repairs or the reposition of defective products above described) directly or indirectly caused by inadequate tests, application, operation or repair of SMAR products.
- 13. It is the customer's responsibility to clean and decontaminate products and accessories prior to shipping them for repair, and SMAR and its dealer reserve themselves the right to refuse the service in cases not compliant to those conditions. It is the customer's responsibility to tell SMAR and its dealer when the product was utilized in applications that contaminate the equipment with harmful products during its handling and repair. Any other damages, consequences, indemnity claims, expenses and other costs caused by the lack of decontamination will be attributed to the client. Kindly, fill out the Declaration of Decontamination prior to shipping products to SMAR or its dealers, which can be accessed at www.smar.com/doc/declarationofcontamination.pdf and include in the packaging.
- 14. This warranty certificate is valid only when accompanying the purchase invoice.